

Does Leveraging the Human Ventral Visual Stream Improve Neural Network Robustness?

Zhenan Shao¹, Linjian Ma², Bo Li^{2,3}, Diane M. Beck¹

BIAI 03/21/2024

¹Department of Psychology, UIUC

²Department of Computer Science, UIUC

³Department of Computer Science, UChicago

Introduction

Robust human vision and vulnerable machine vision



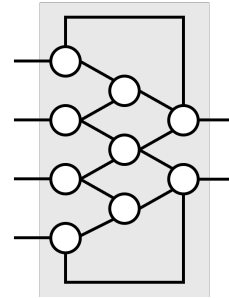
Human visual perception
achieves various invariance

Biederman & Cooper, 1991;

Cave, Bost & Cobb, 1996;

Biederman & Gerhardstein, 1993;

...



Even imperceptible
perturbations can lead to
wrong prediction

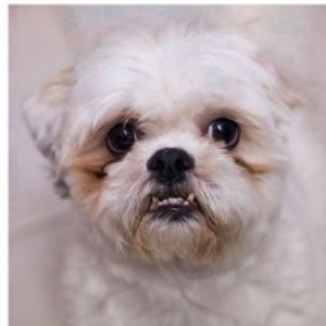
Szegedy et al., 2014;

Carlini & Wagner, 2017;

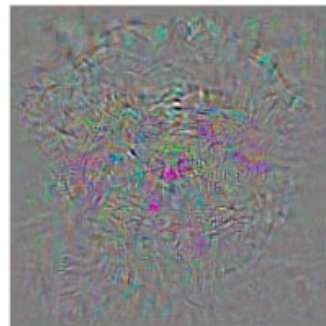
Kurakin et al., 2017;

...

dog

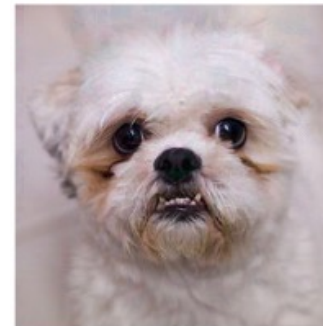


+



=

Ostrich

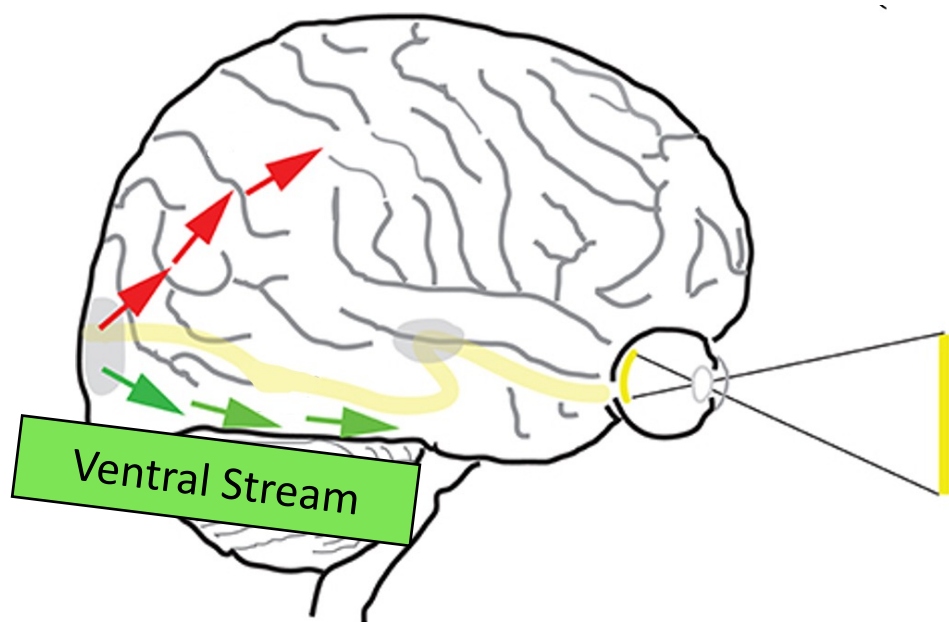


(Szegedy et al., 2014)

Introduction

Achieving invariances along visual ventral stream

- The ventral visual stream forms a hierarchy, transitioning from basic visuals to more abstract and stable representations (Logothetis and Sheinberg, 1996, Zoccolan et al., 2007, Isik et al., 2014, Jordan et al., 2015...).
- Evolving representations space achieved by separating object manifolds (Dicarlo & Cox, 2007).

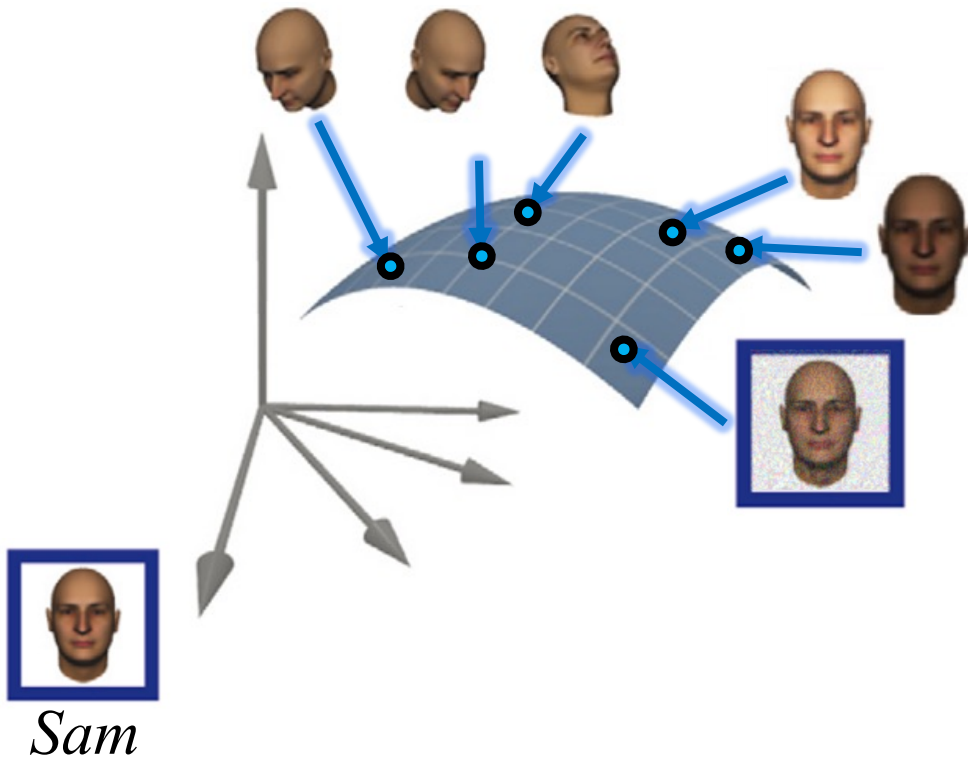


(Sheth & Young, 2016)

Introduction

Achieving invariances along visual ventral stream

- The ventral visual stream forms a hierarchy, transitioning from basic visuals to more abstract and stable representations (Logothetis and Sheinberg, 1996, Zoccolan et al., 2007, Isik et al., 2014, Jordan et al., 2015...).
- Evolving representations space achieved by separating object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

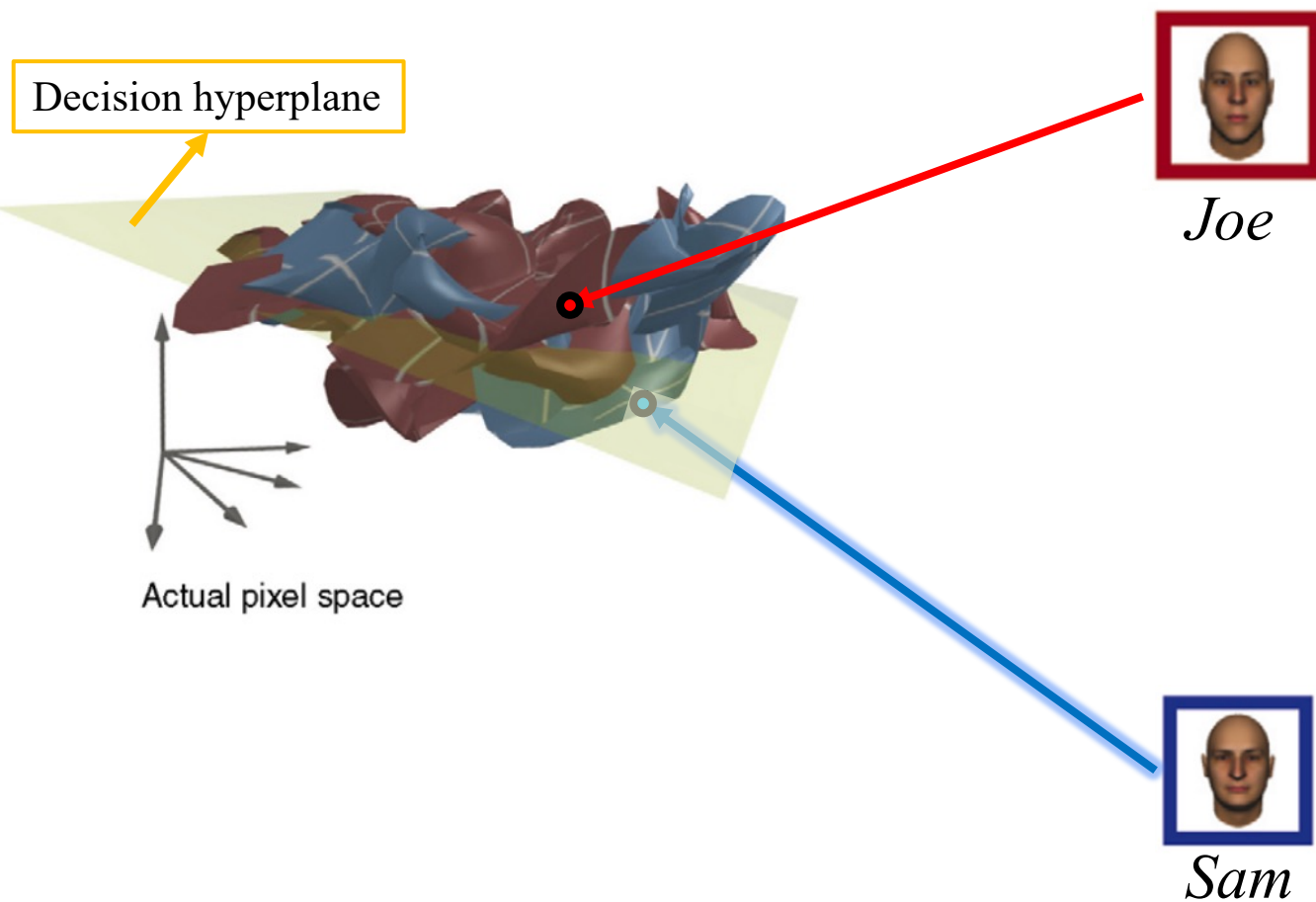
- The ventral visual stream forms a hierarchy, transitioning from basic visuals to more abstract and stable representations (Logothetis and Sheinberg, 1996, Zoccolan et al., 2007, Isik et al., 2014, Jordan et al., 2015...).
- Evolving representations space achieved by separating object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

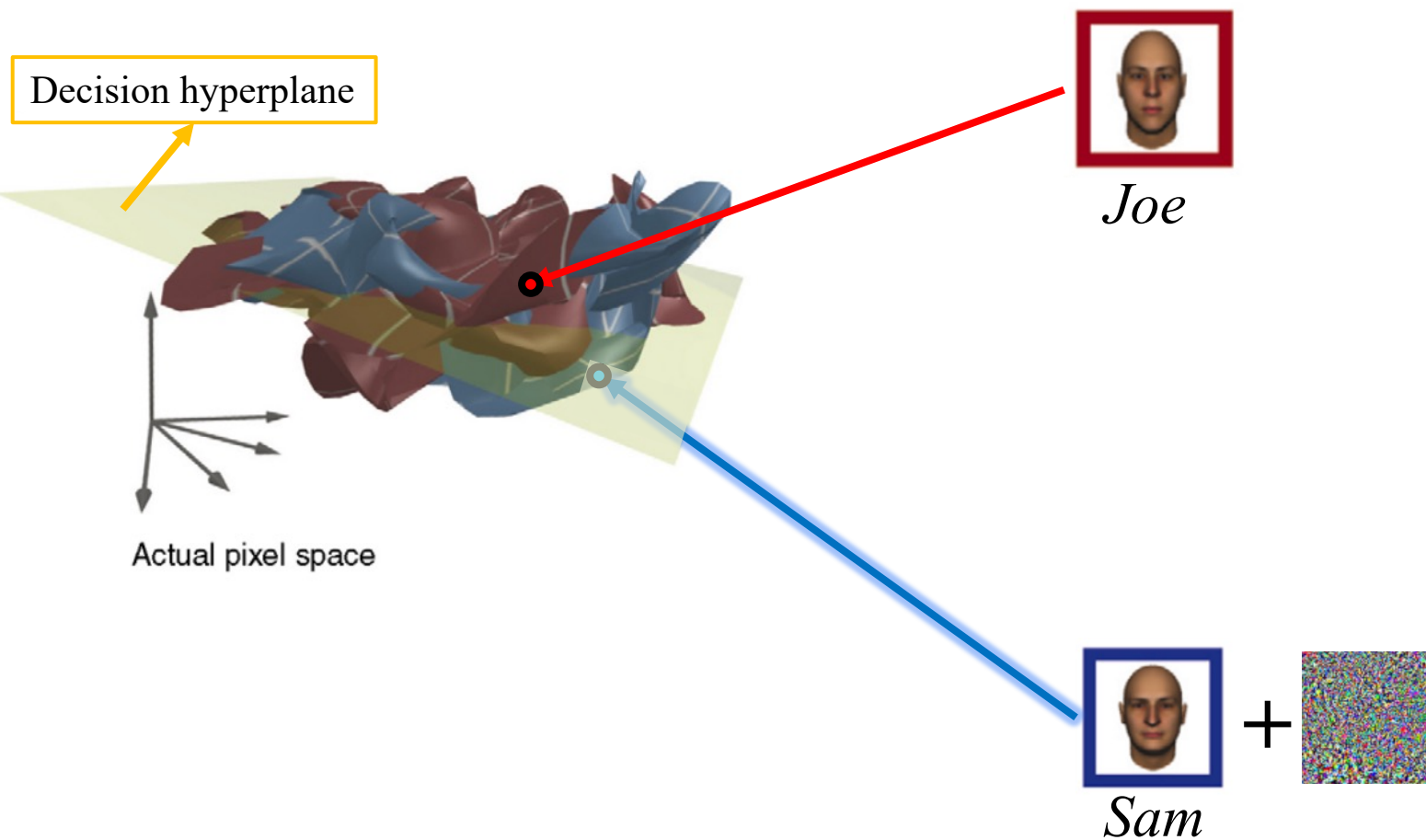
- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

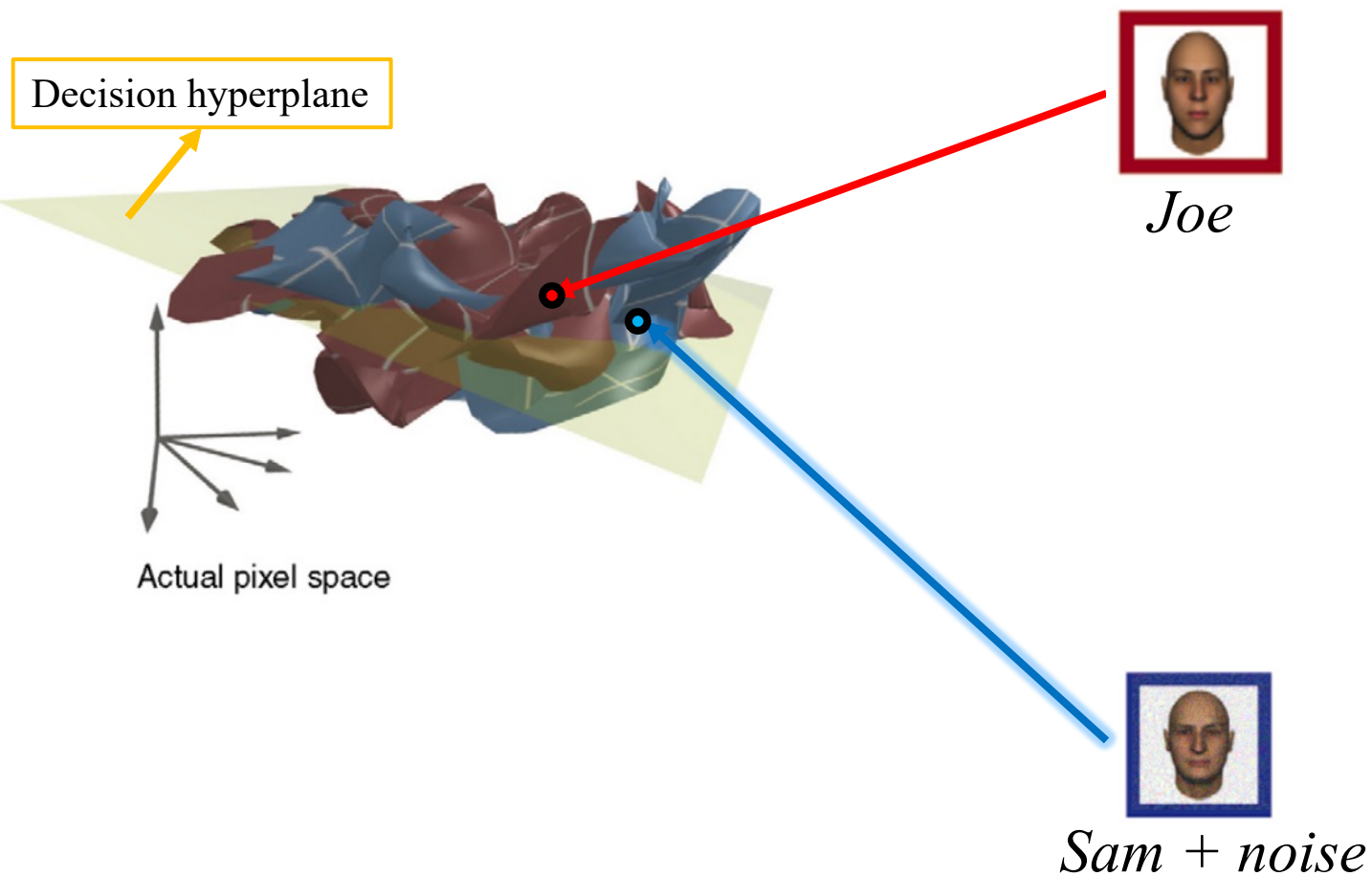
- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

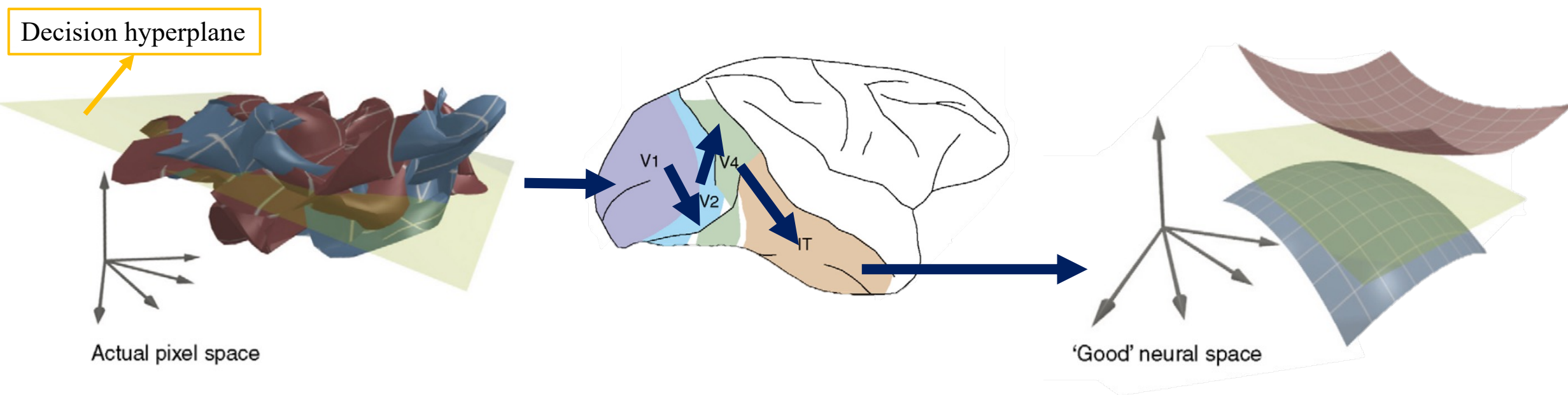
- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

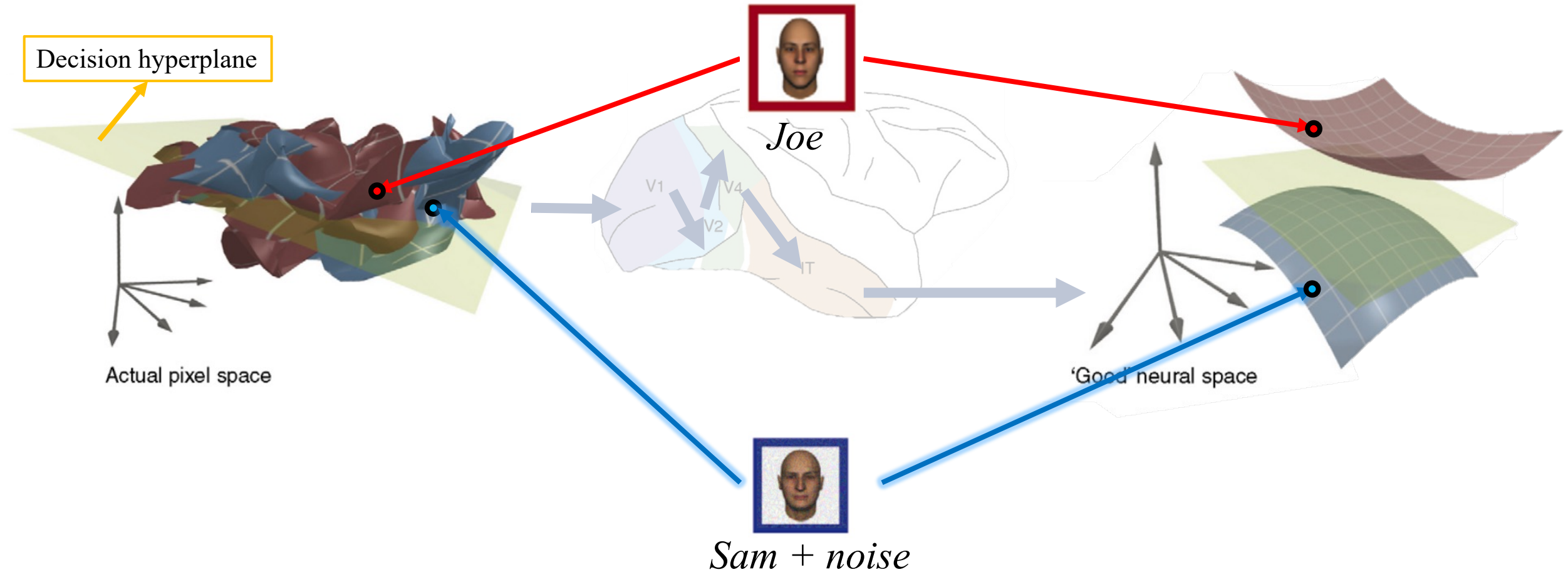
- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



Introduction

Achieving invariances along visual ventral stream

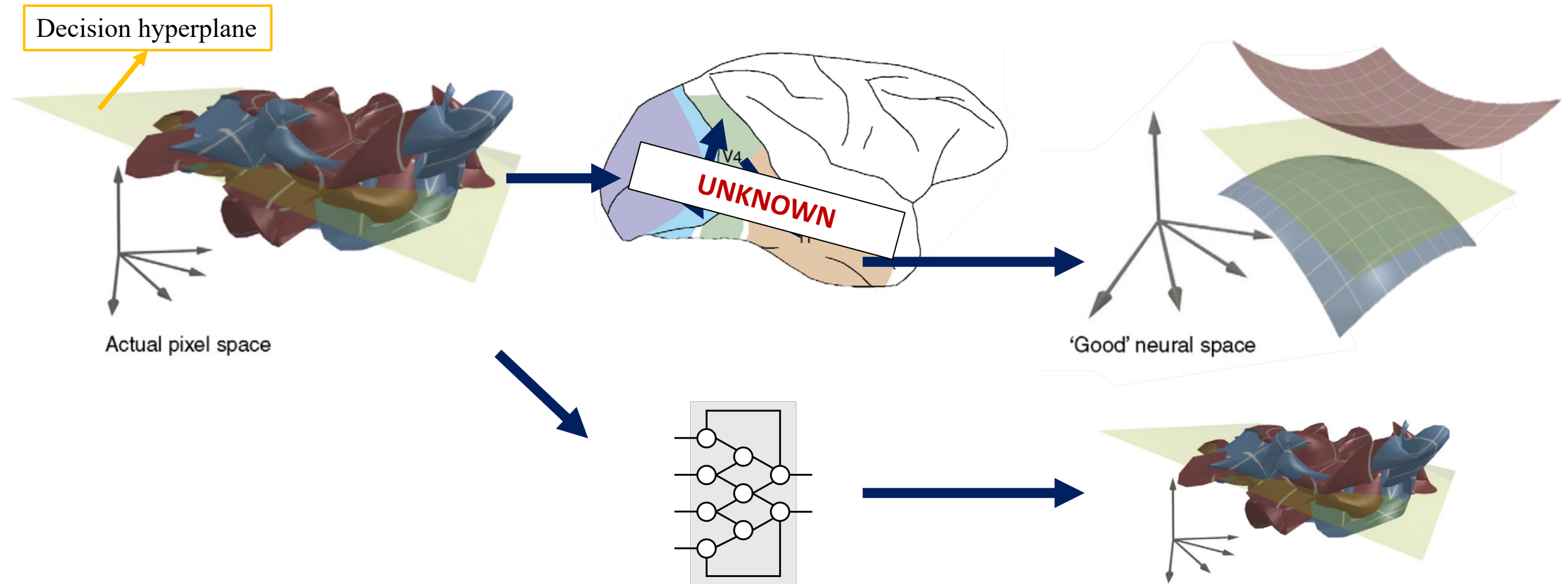
- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



Introduction

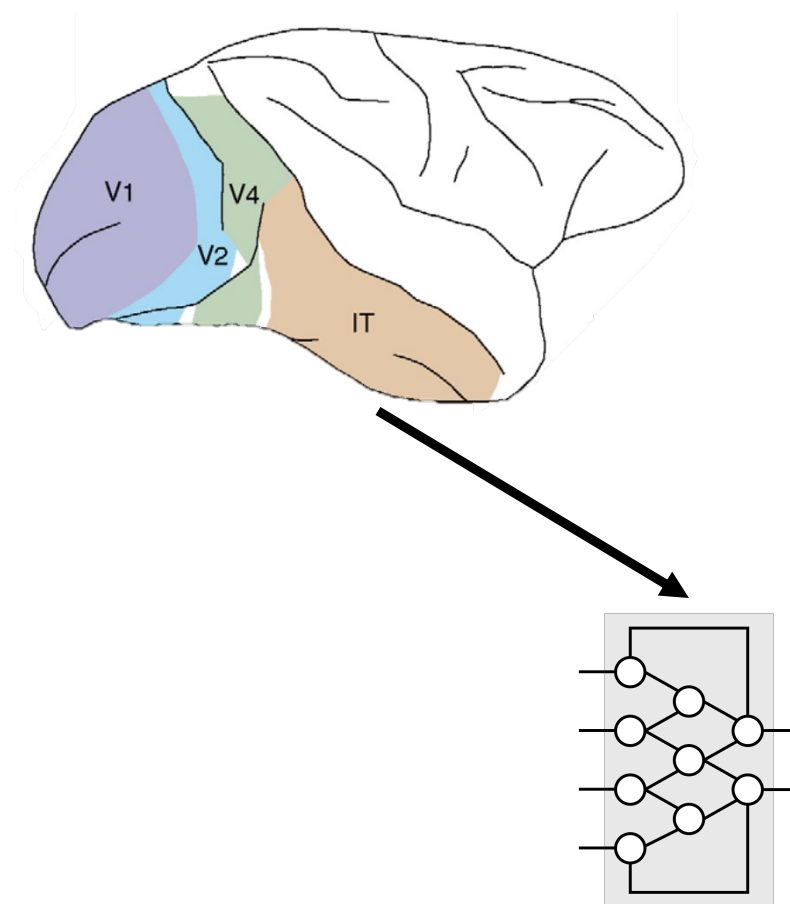
Achieving invariances along visual ventral stream

- Evolving representations achieved more separable object manifolds (Dicarlo & Cox, 2007).



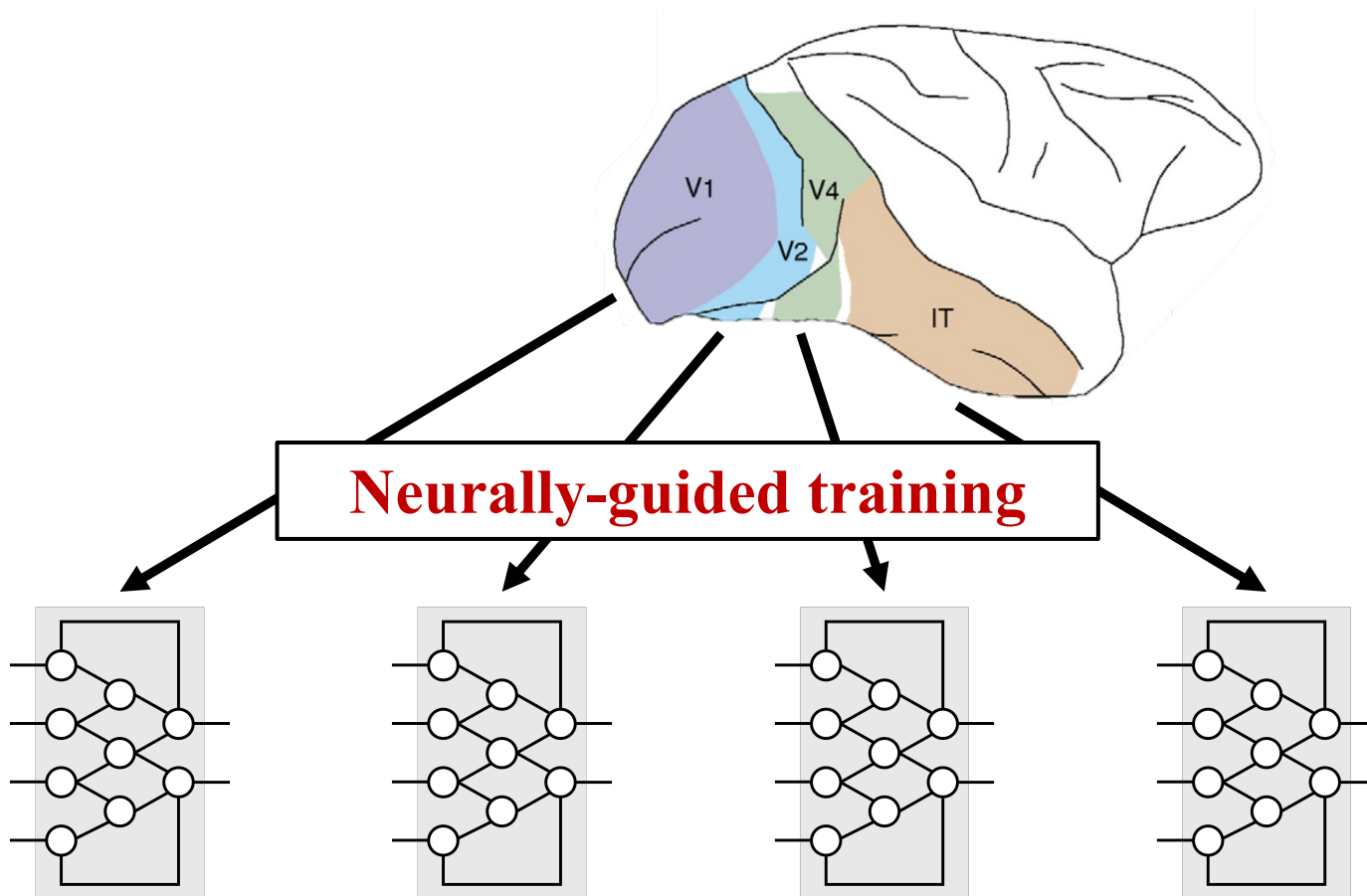
Our question

1. Does training guided by human ventral cortex activity improve neural network robustness?



Our question

1. Does training guided by human ventral cortex activity improve neural network robustness?
2. Does such improvement increase as we ascend the ventral visual cortex?

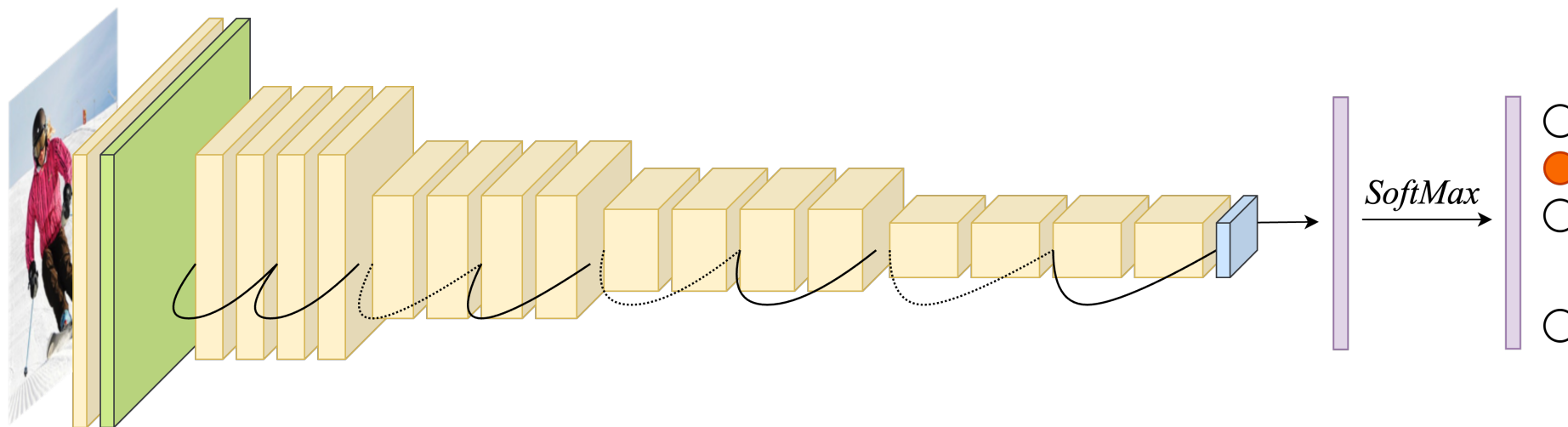



Method

Neurally-guided training

- DNN visual task training:

$$L = L_{task}$$



 Max Pooling

 Avg Pooling

 Conv

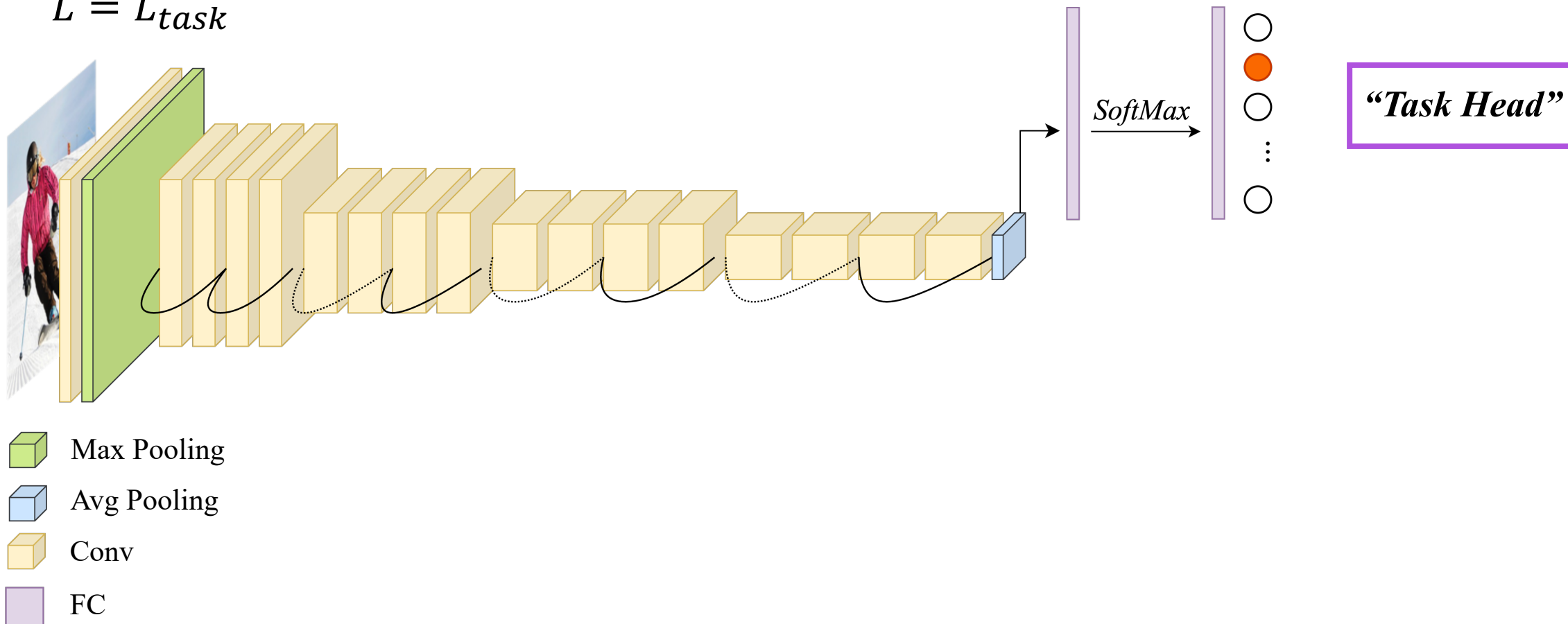
 FC

Method

Neurally-guided training

- DNN visual task training:

$$L = L_{task}$$

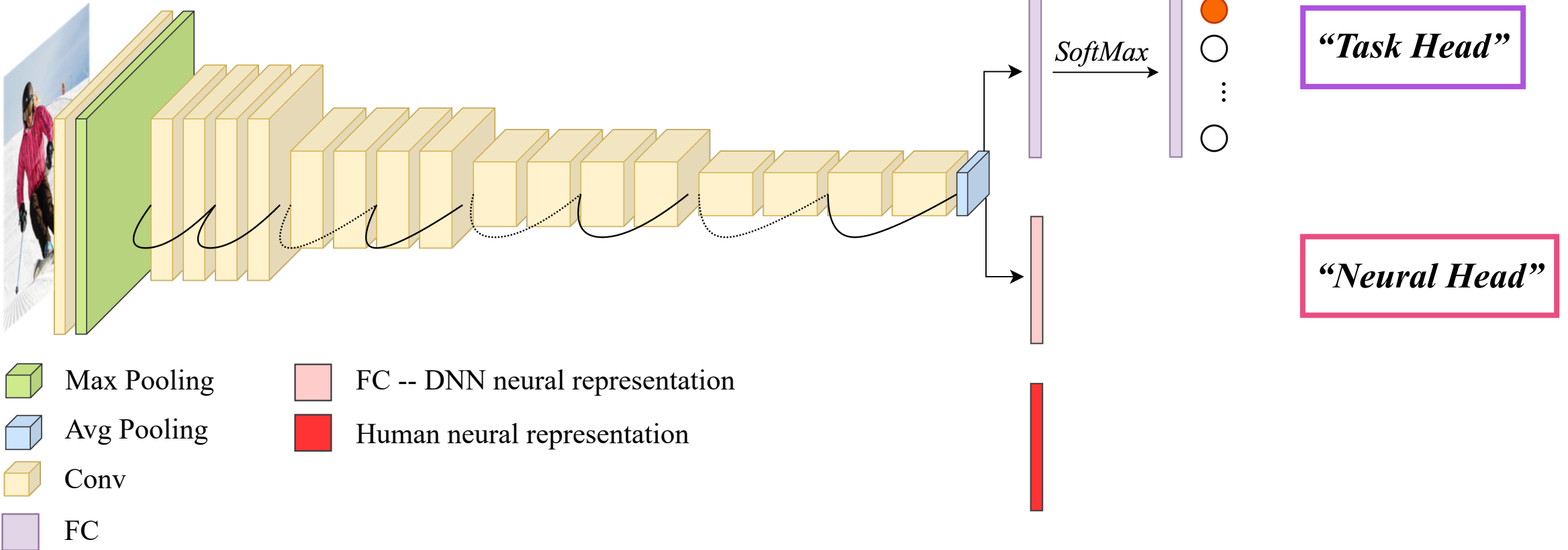


Method

Neurally-guided training

- DNN visual task training with **Neural Guidance**:

$$L = L_{task}$$

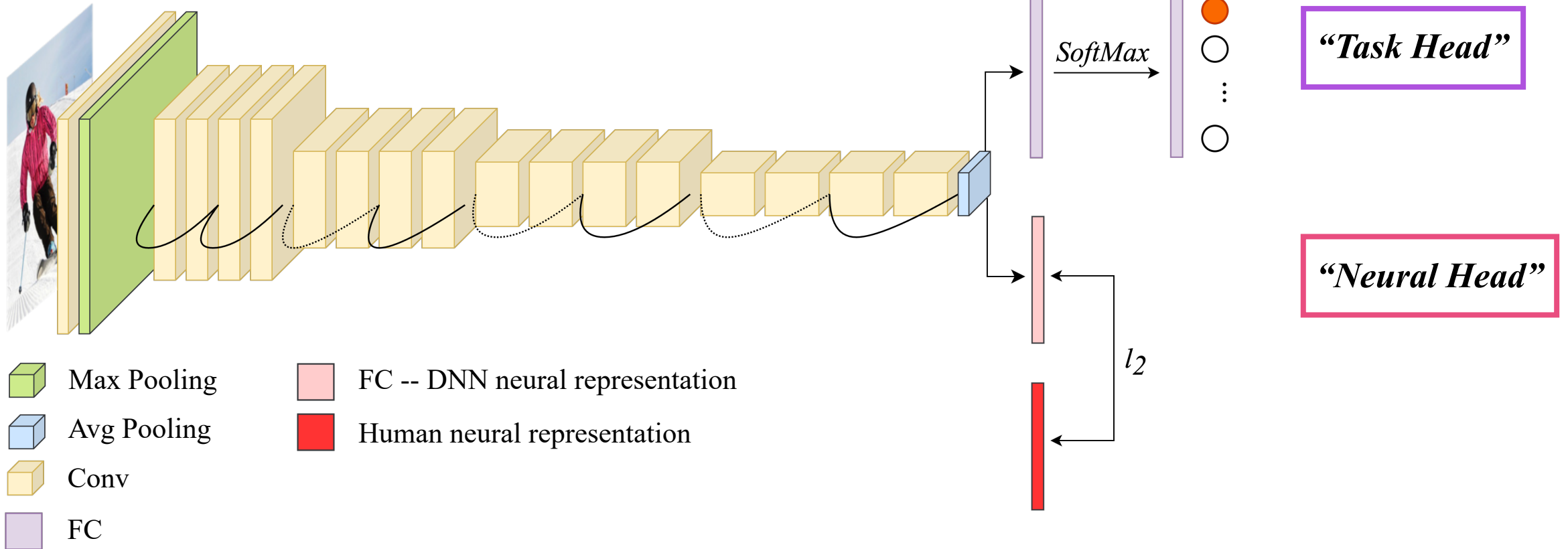


Method

Neurally-guided training

- DNN visual task training with **Neural Guidance**:

$$L = L_{task} + \|R_{DNN} - R_{neural}\|_2$$

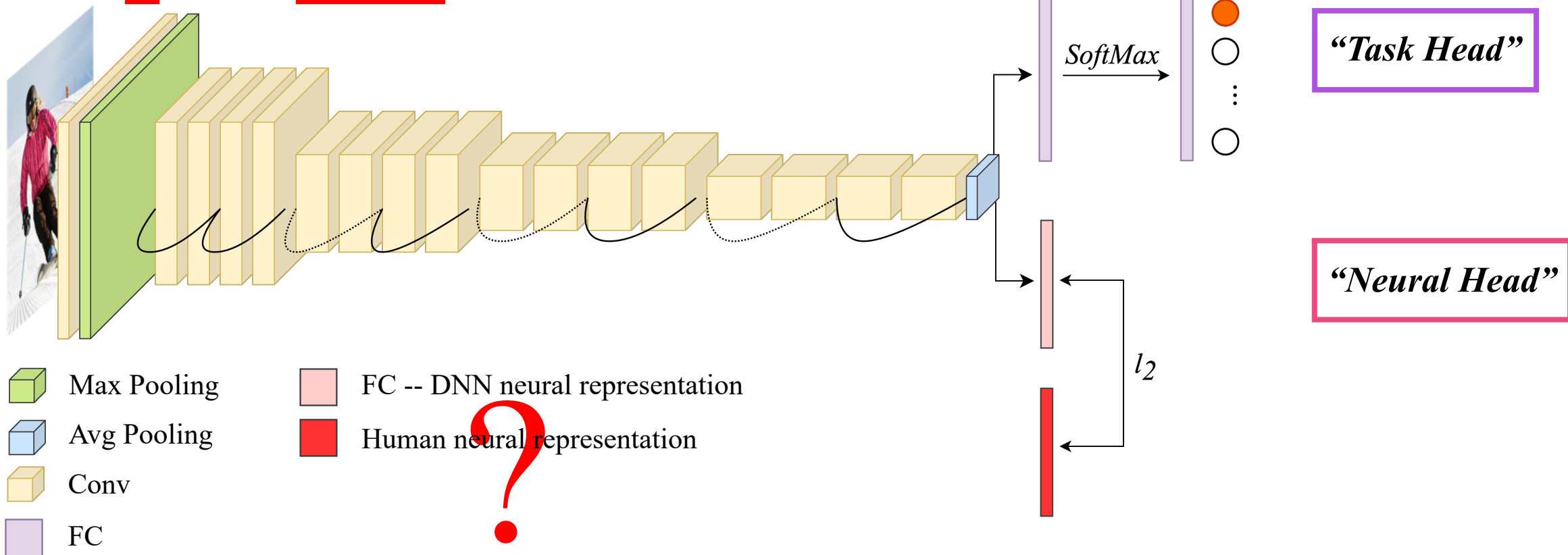


Method

Neurally-guided training

- DNN visual task training with **Neural Guidance**:

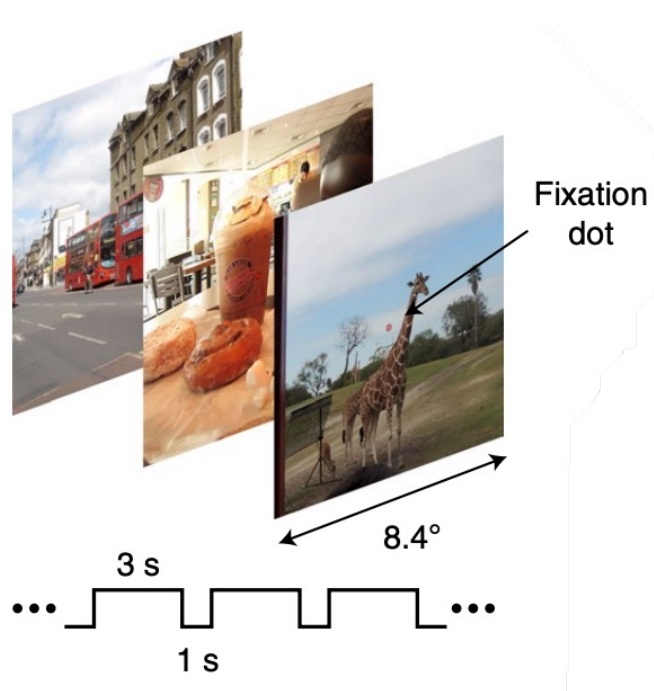
$$L = \alpha L_{task} + (1 - \alpha) \|R_{DNN} - R_{neural}\|_2$$



Method

Neural data

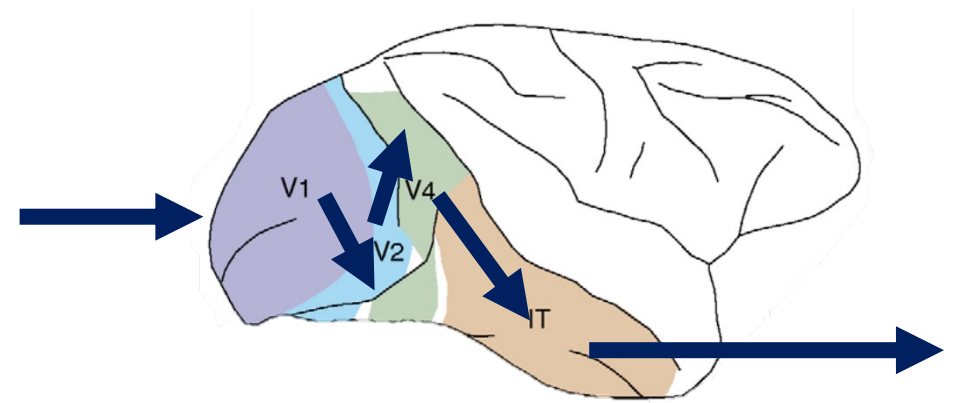
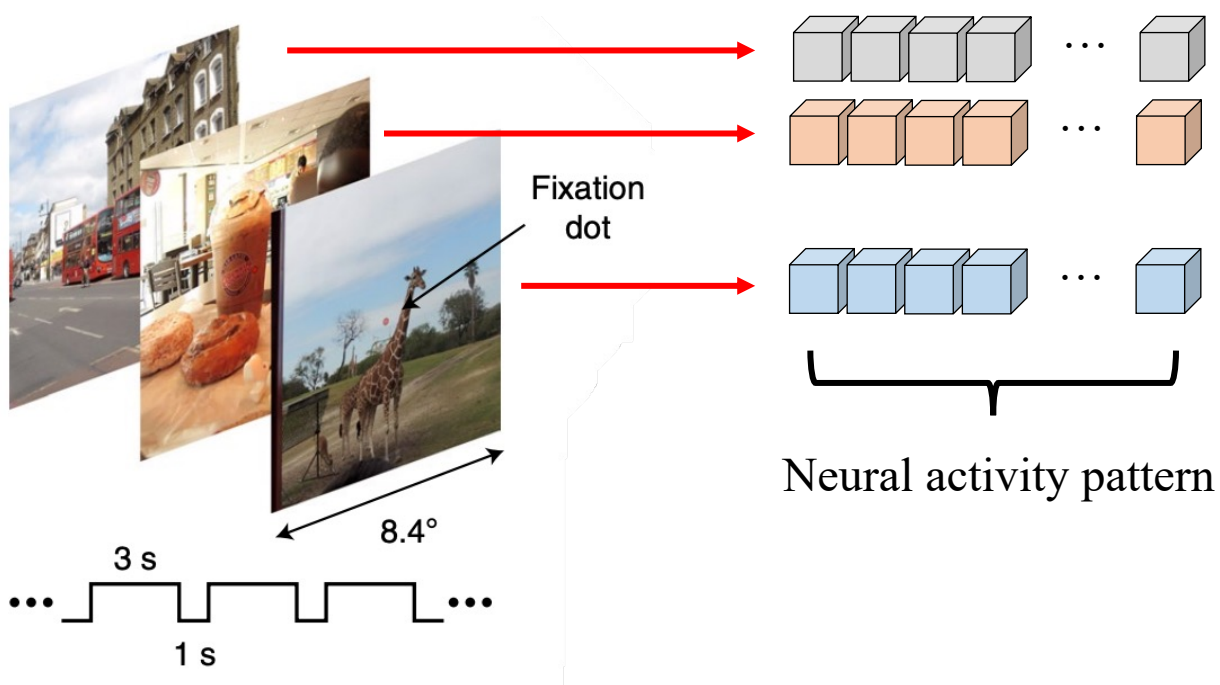
- Each human subject viewed $\sim 30,000$ images ($\sim 9,000$ unique).
- Brain activities were recorded with 7T fMRI.



Method

Neural data

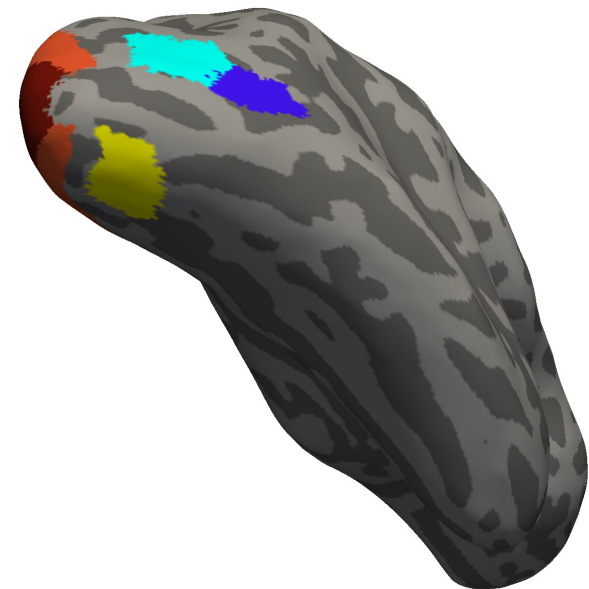
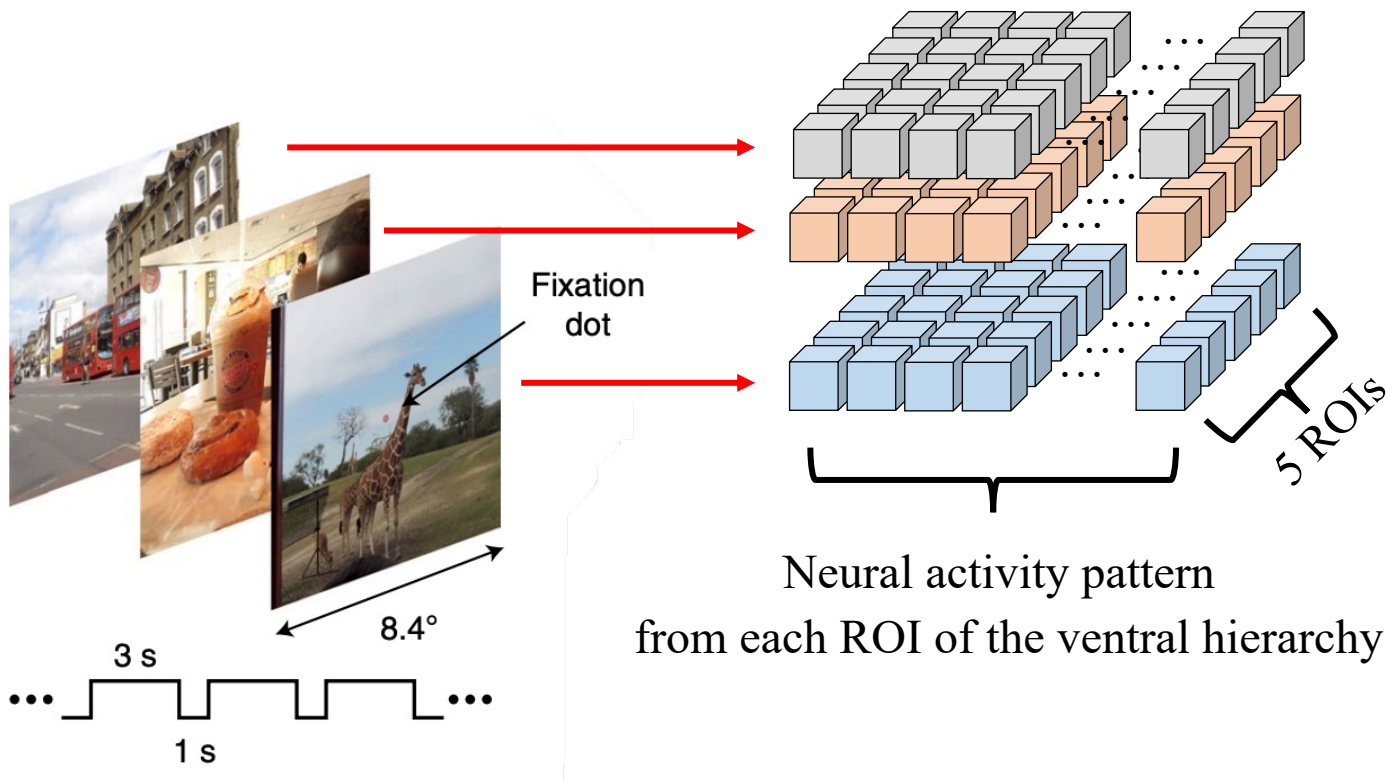
- Each human subject viewed $\sim 30,000$ images ($\sim 9,000$ unique).
- Brain activities were recorded with 7T fMRI.



Method

Neural data

- Each human subject viewed $\sim 30,000$ images ($\sim 9,000$ unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral Regions of Interest (**ROIs**) were used

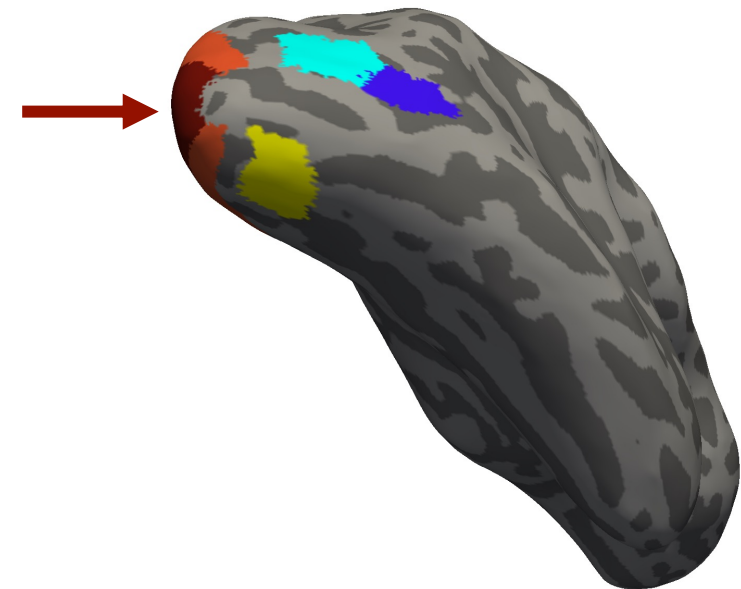
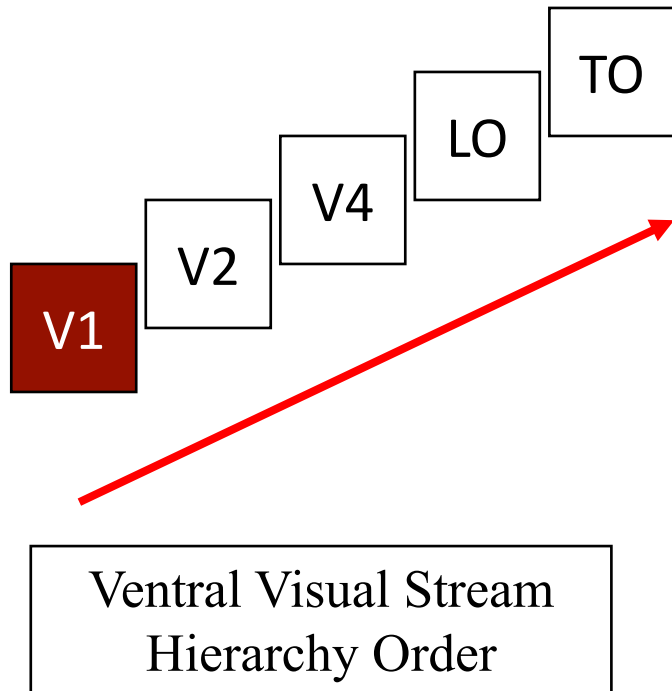


Subject 1 ROIs

Method

Neural data

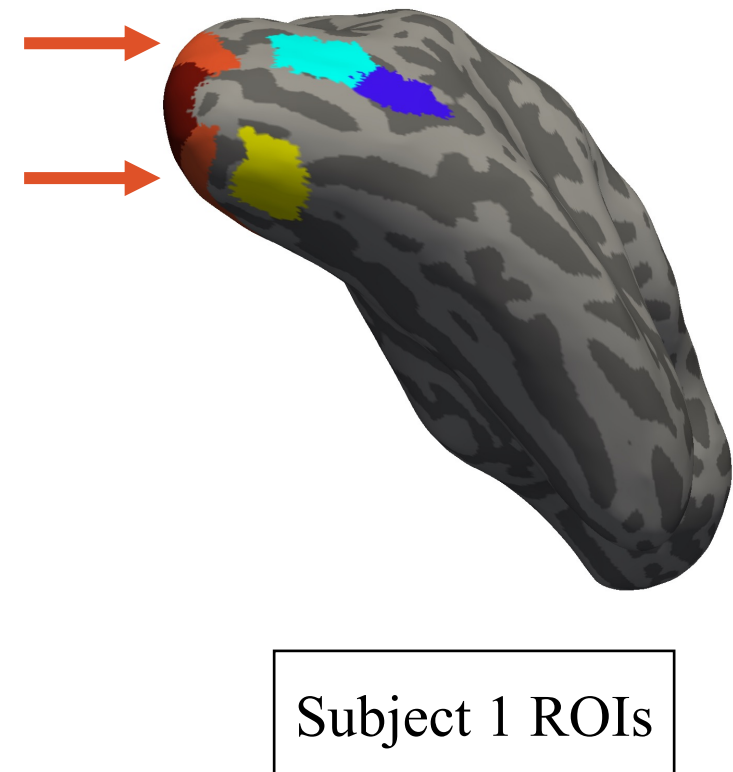
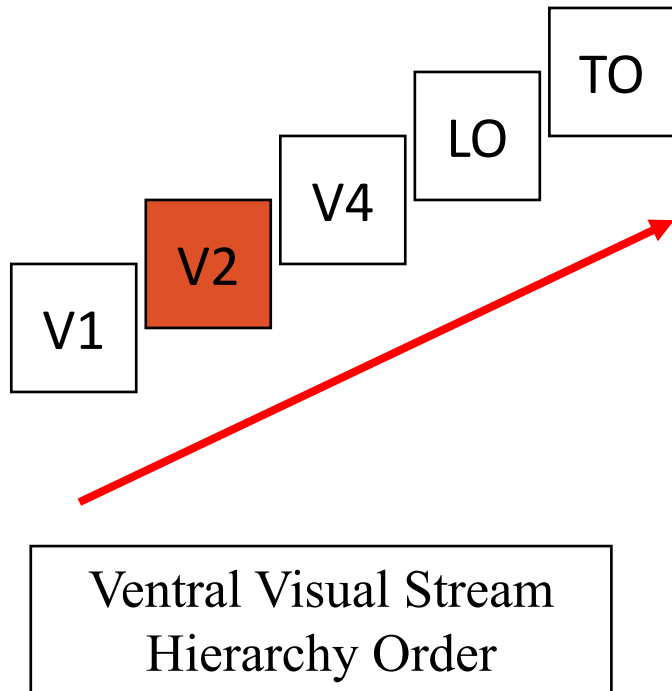
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

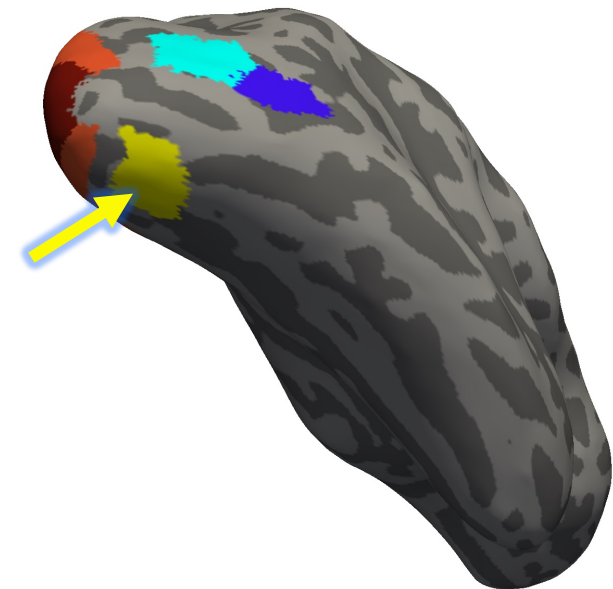
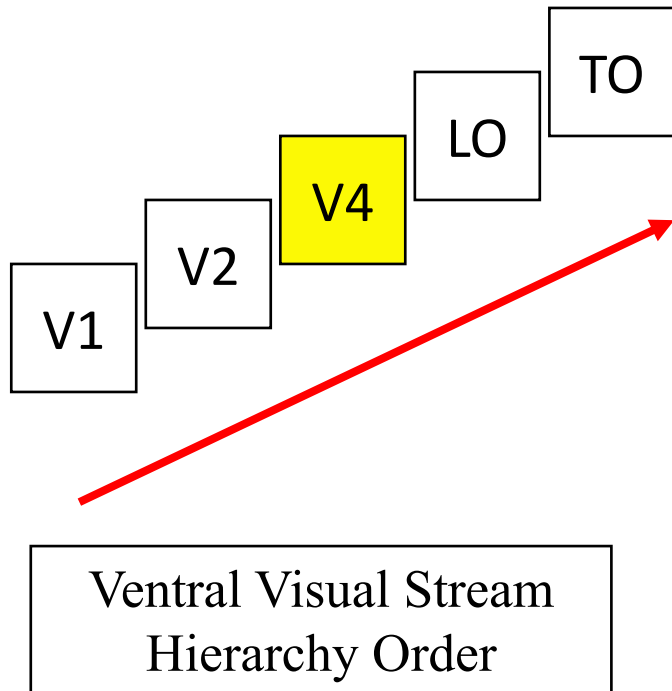
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

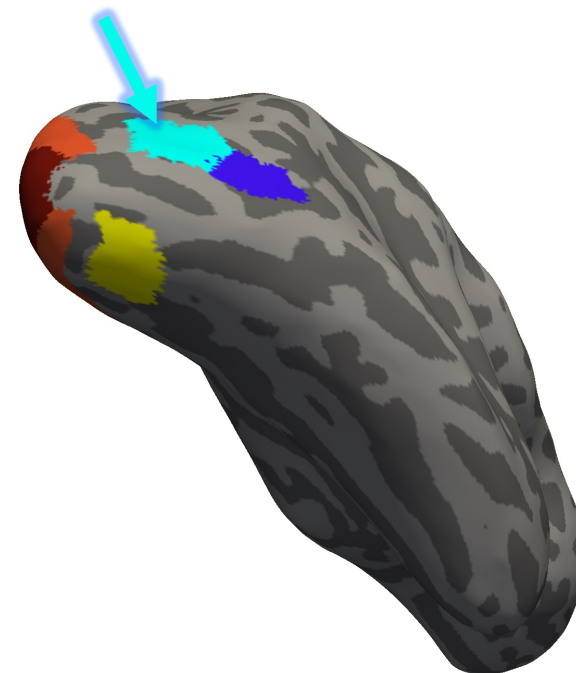
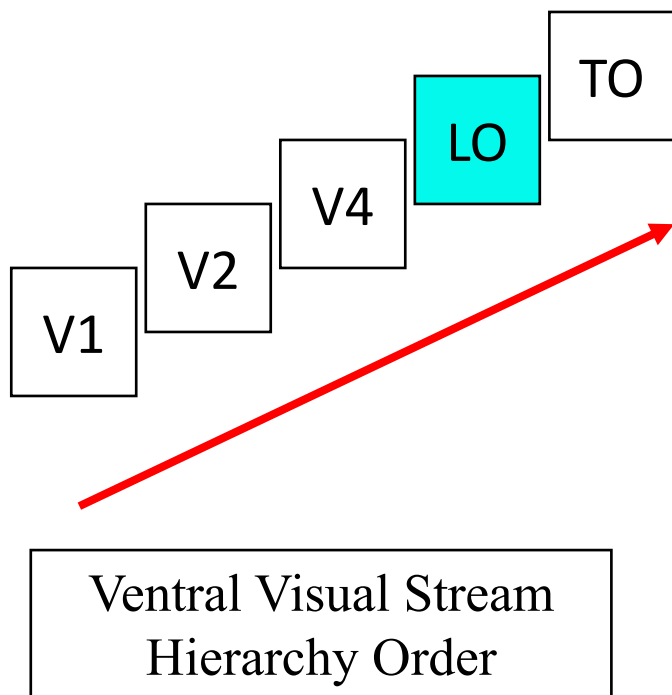
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

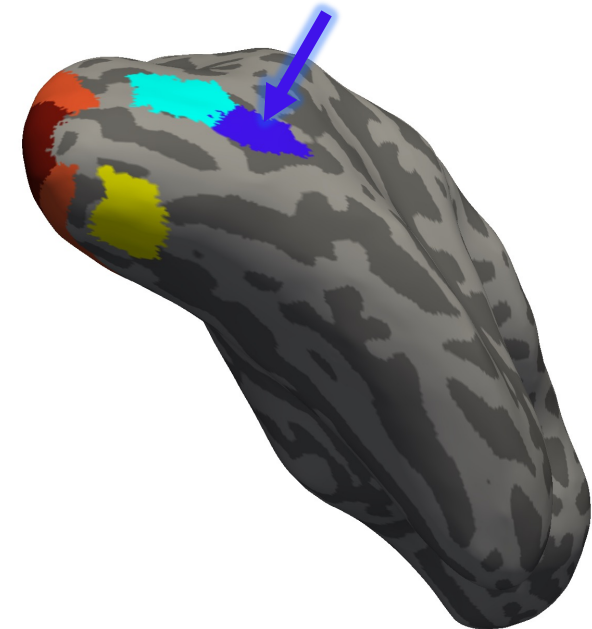
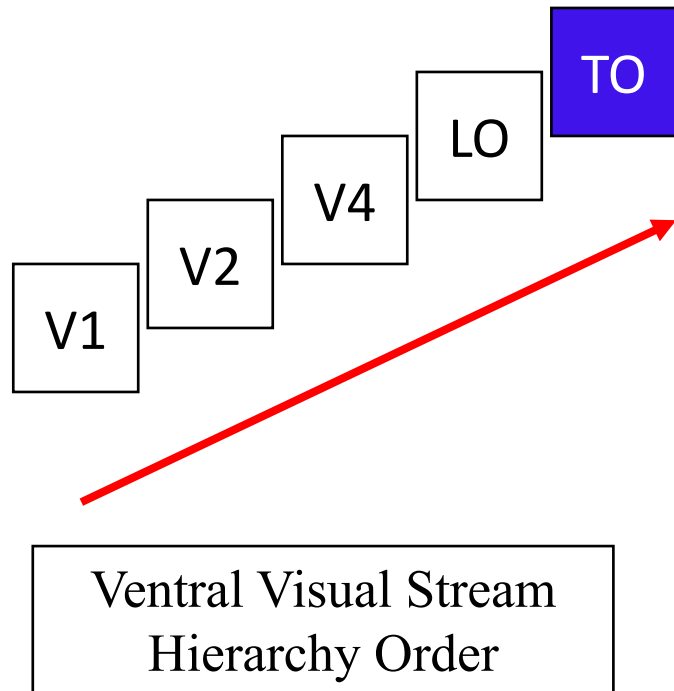
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

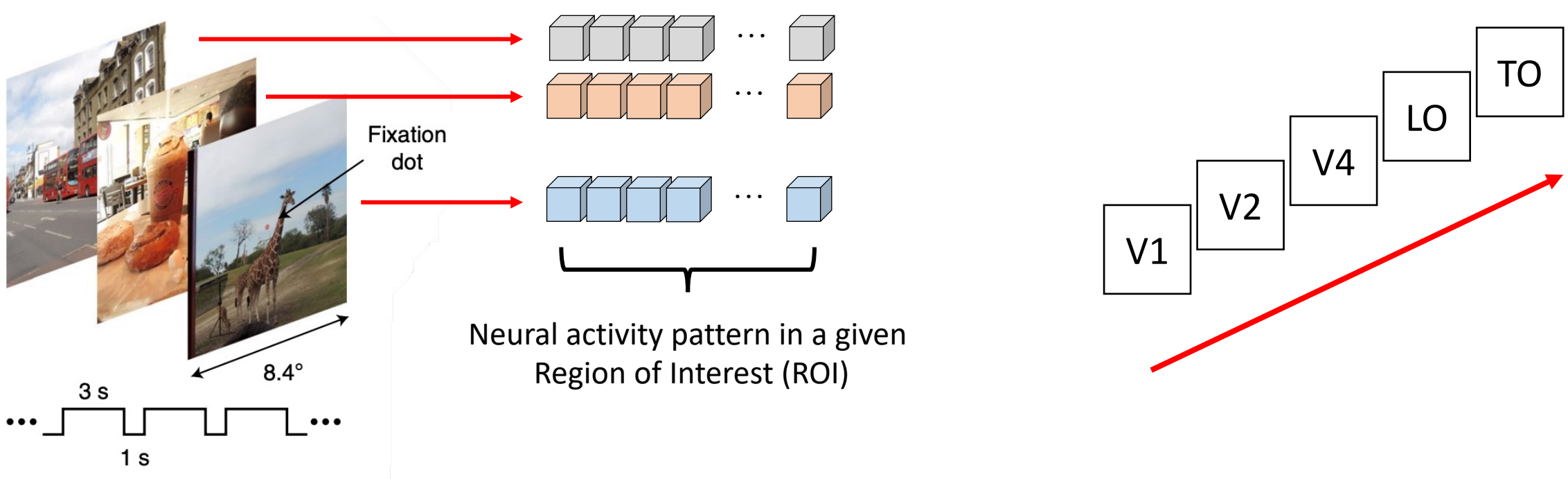
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

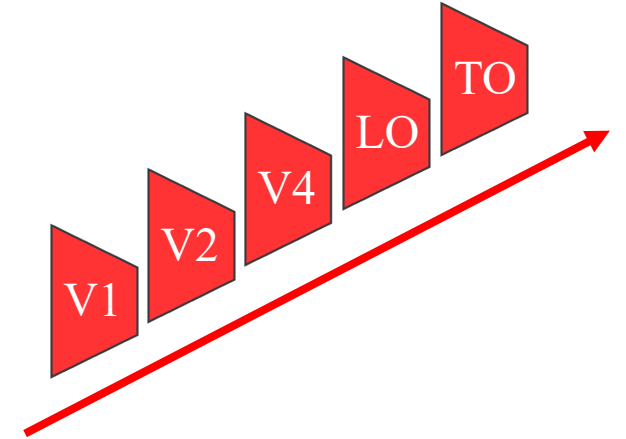
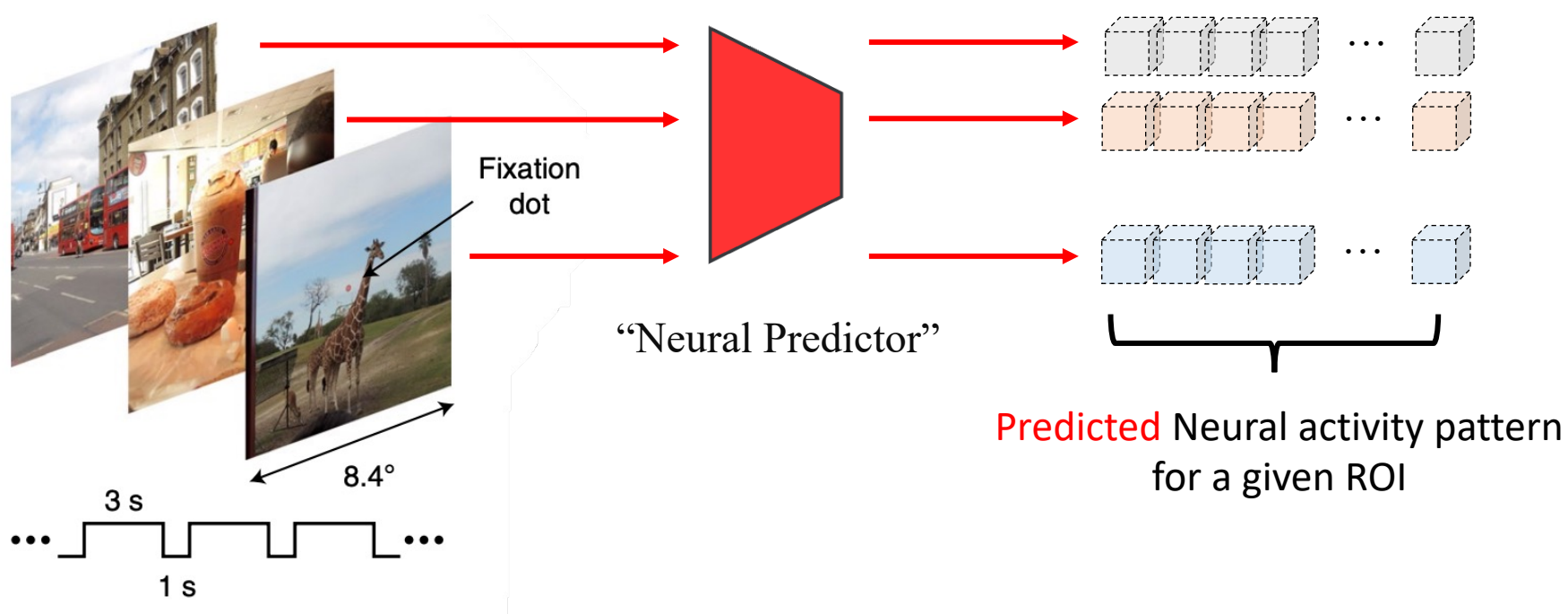
- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used:



Method

Neural data

- Each human subject viewed ~30,000 images (~9,000 unique).
- Brain activities were recorded with 7T fMRI.
- 5 bilateral ROIs were used.

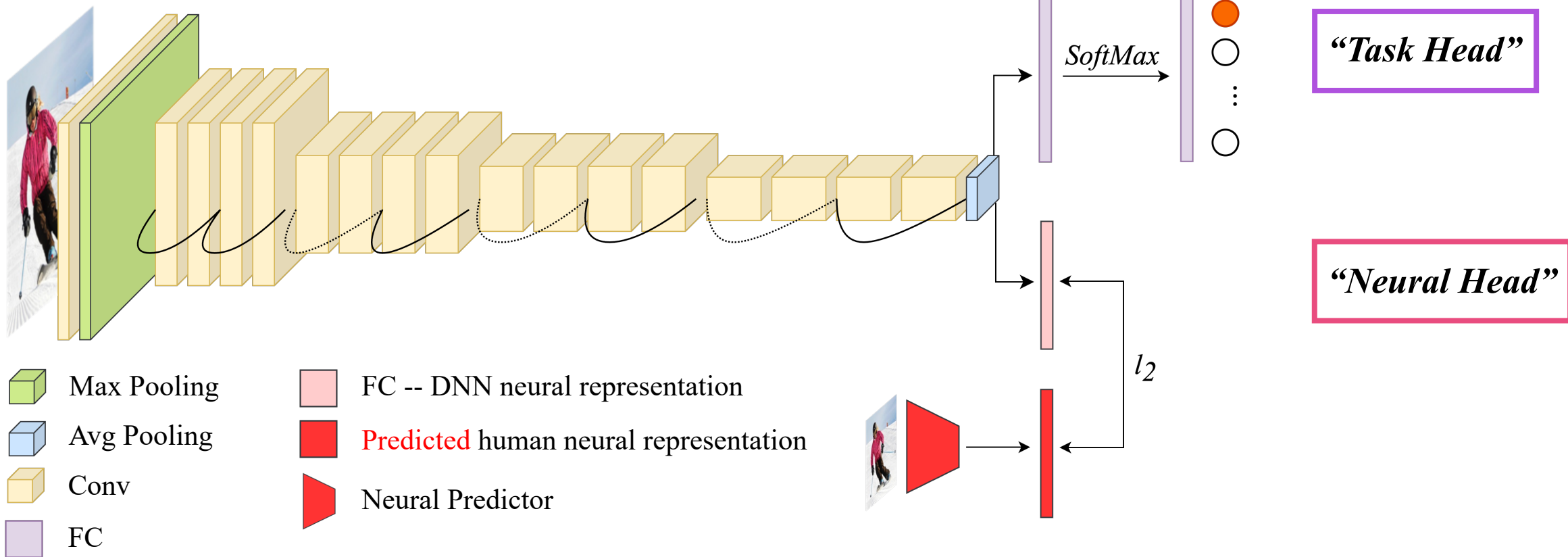


Method

Neurally-guided training

- DNN visual task training with **Neural Guidance**:

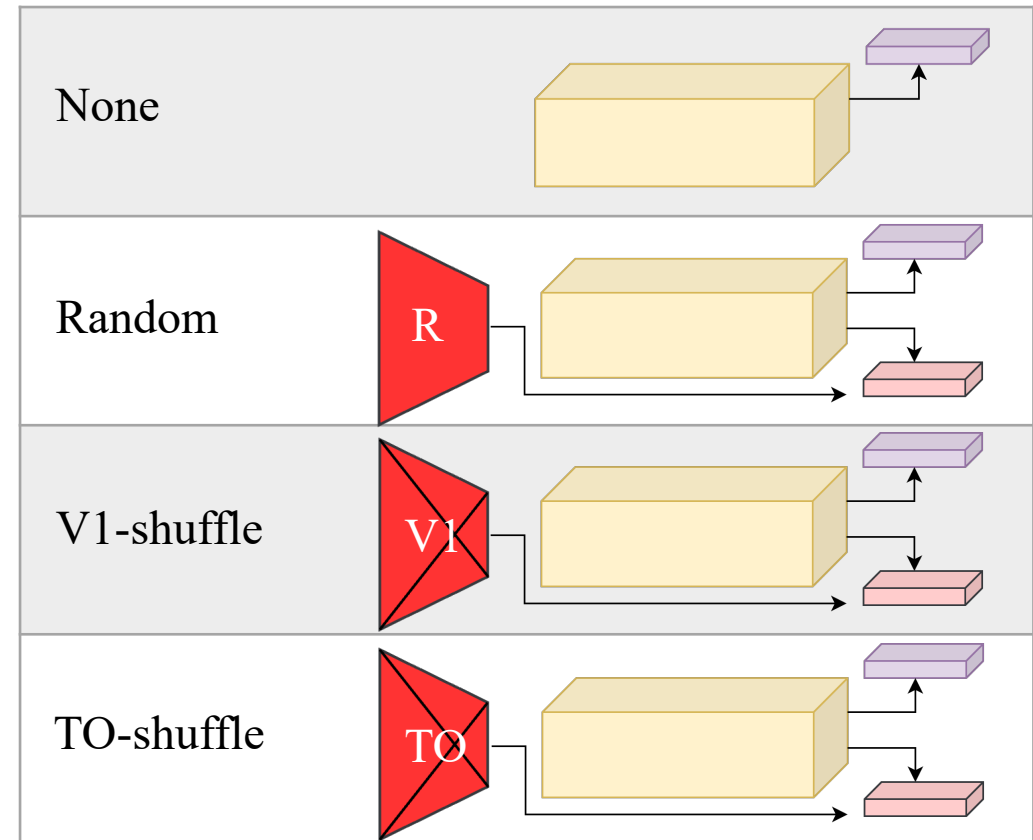
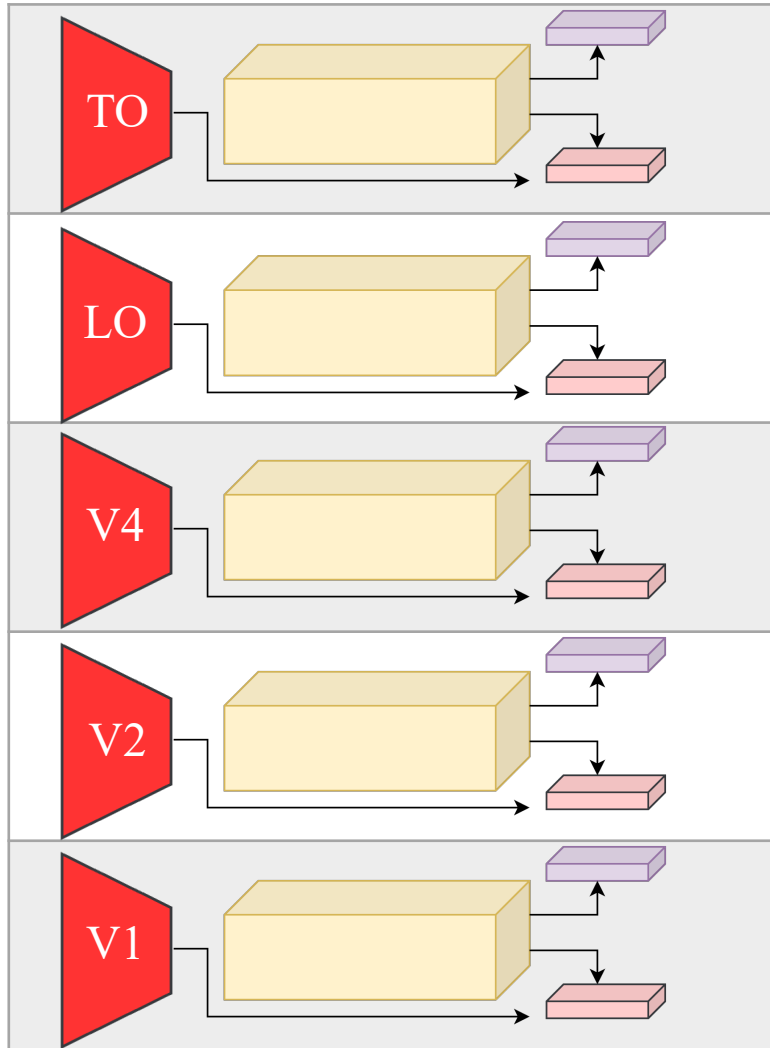
$$L = \alpha L_{task} + (1 - \alpha) ||R_{DNN} - R_{human} ||_2$$



Method

Summary of models

- 5 models with **neural-guided training**
- 4 **baseline models** for comparison



Robustness of Neurally-guided Models

Evaluation

- l_p -based adversarial attack:

$\max_{\|\tau\|_p < \epsilon} l(f_\theta(x + \tau), y)$

dog + [noise] = Ostrich

(Szegedy et al., 2014)

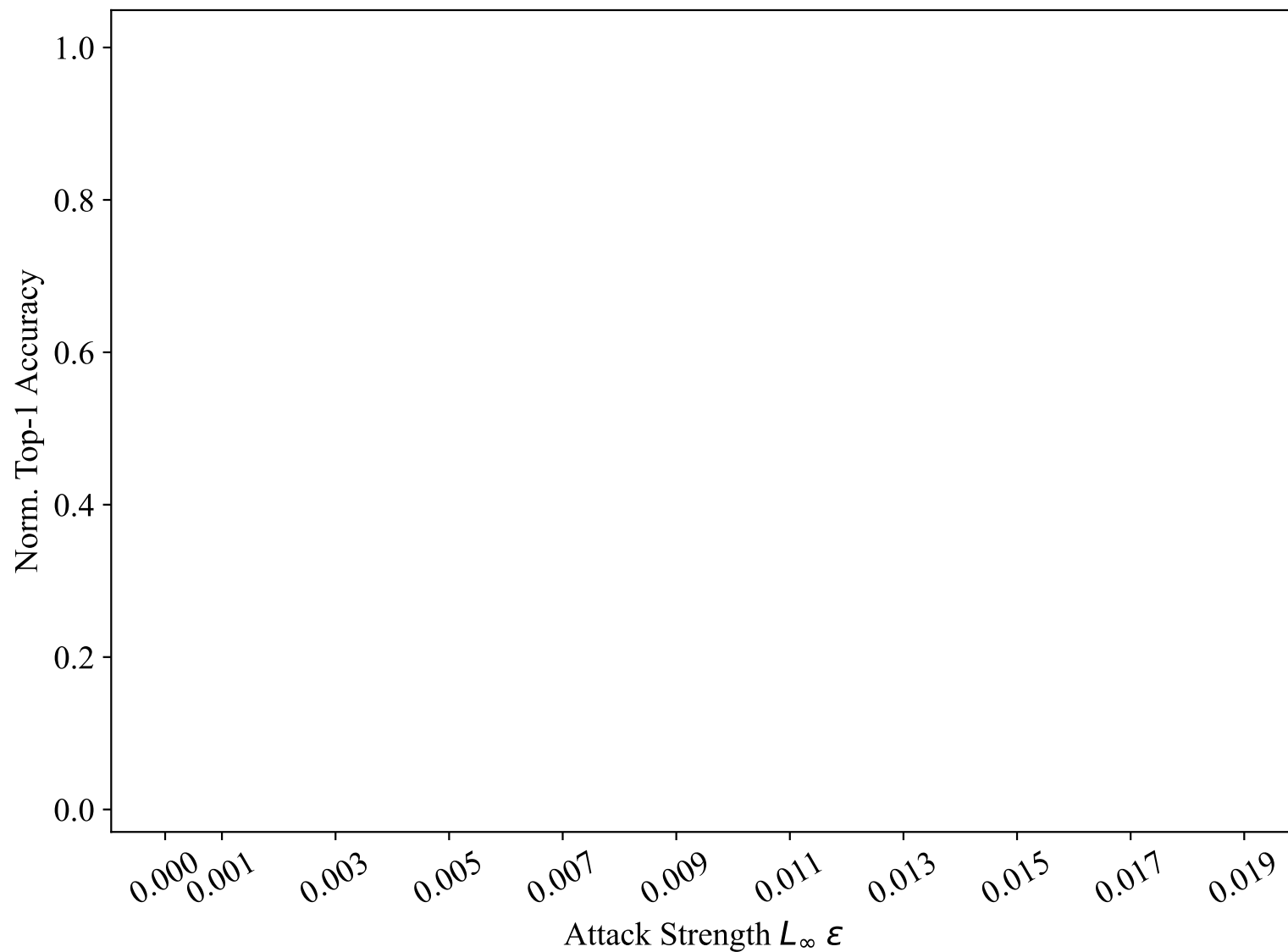
- We check: {
1. Does **neural guidance** improve neural network robustness? ✓/✗
 2. Is such improvement **hierarchical**? ✓/✗

Results

l_∞ -based PGD adversarial attack

Task: Image *Classification*

Dataset: *ImageNet* (Deng et al., 2009)



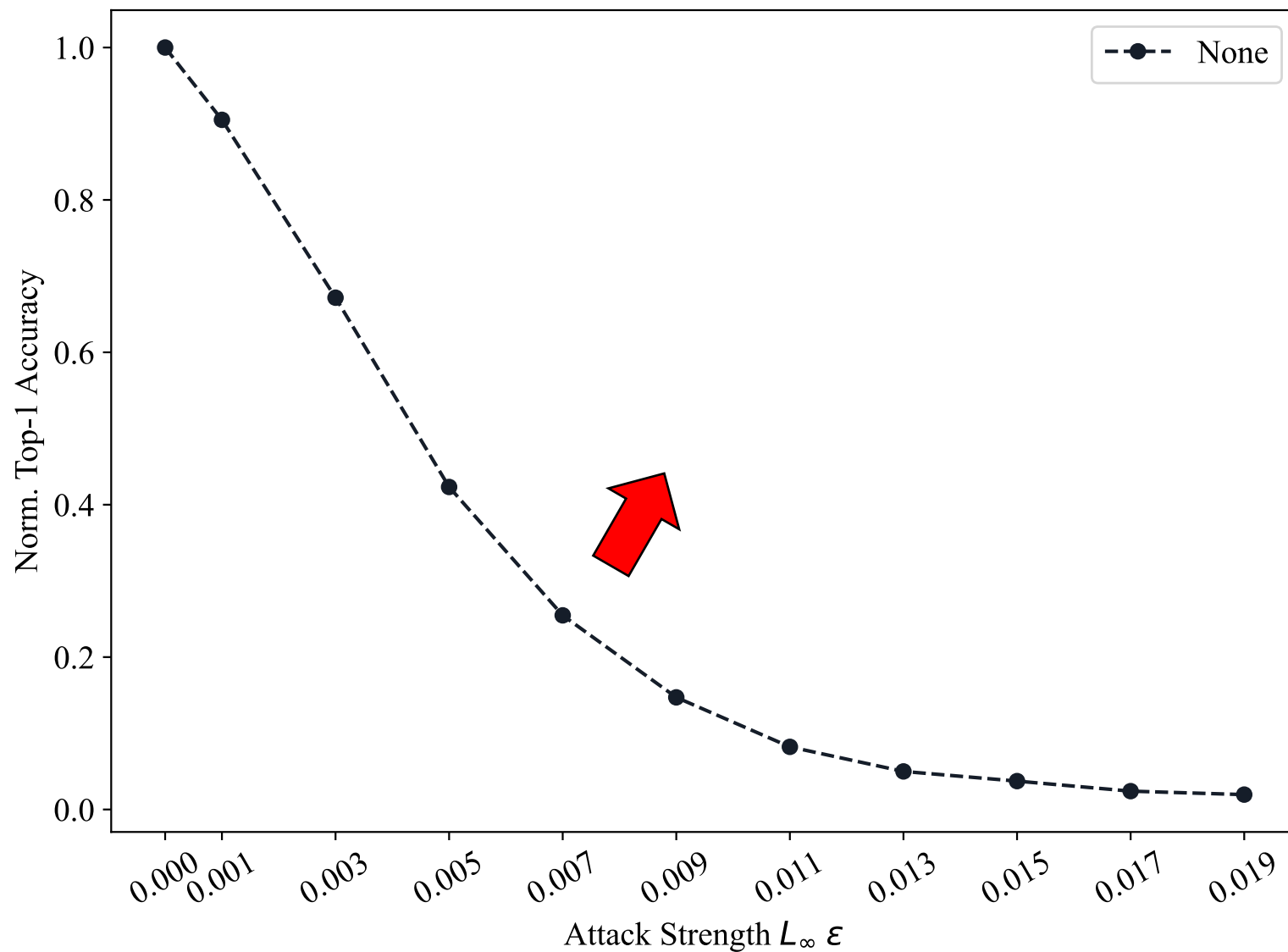
“None”

Results

l_∞ -based PGD adversarial attack

Task: Image *Classification*

Dataset: *ImageNet* (Deng et al., 2009)



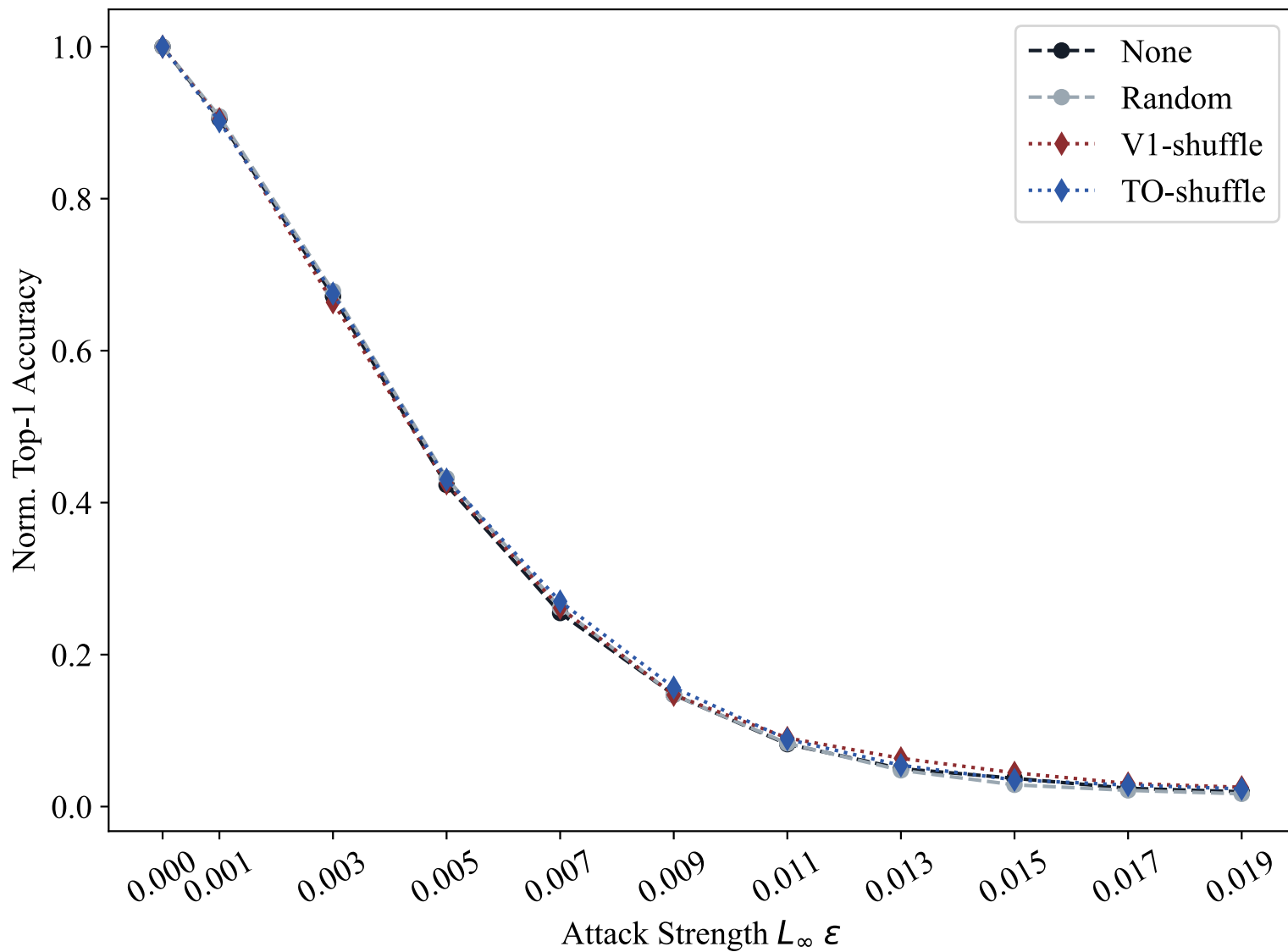
“None”

Results

l_∞ -based PGD adversarial attack

Task: *Image Classification*

Dataset: *ImageNet* (Deng et al., 2009)



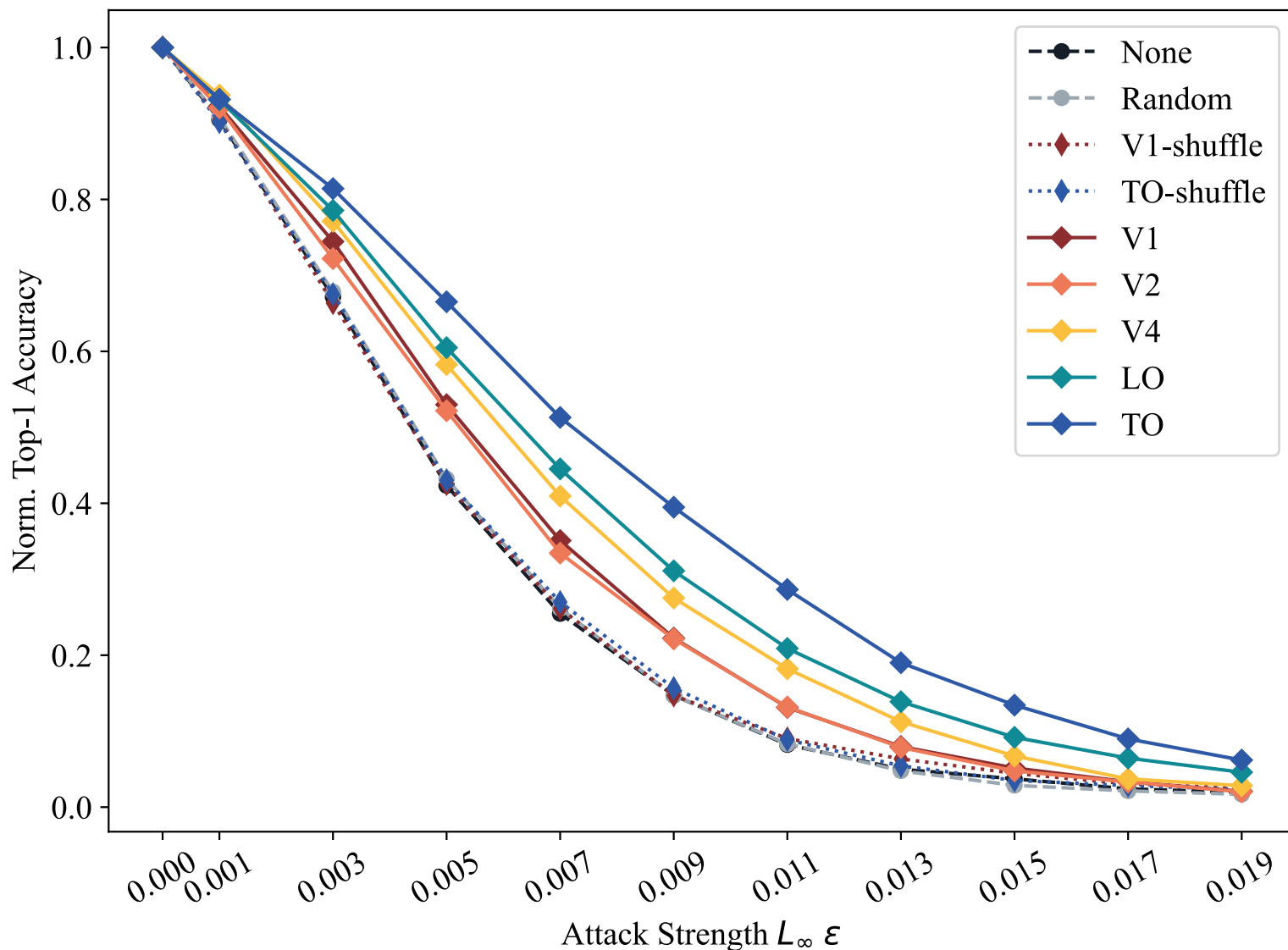
“None” “Random”
“V1-shuffle” “TO-shuffle”


Results

l_∞ -based PGD adversarial attack

Task: *Image Classification*

Dataset: *ImageNet* (Deng et al., 2009)



- **Neural guidance improves robustness** (max: 22% accuracy increase) 

- **There exists a hierarchy of improvement's magnitude** 

- **Similar results have been observed with:**

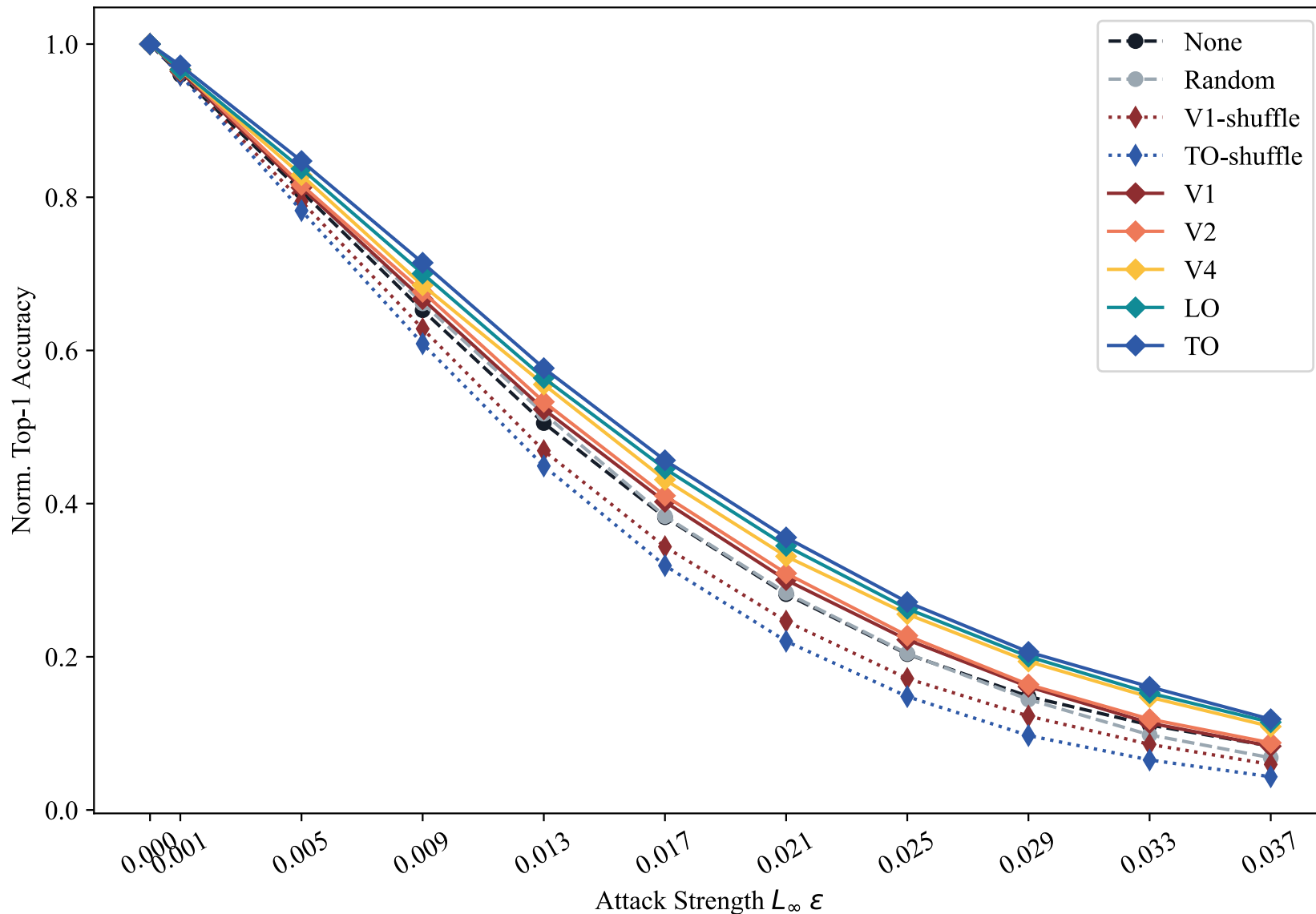
- L_∞ FGSM
- Auto-Attack (APGD-CE, APGD-T, FAB square)
- L_2 FGM
- L_2 Deepfool

Results

l_∞ -based PGD adversarial attack

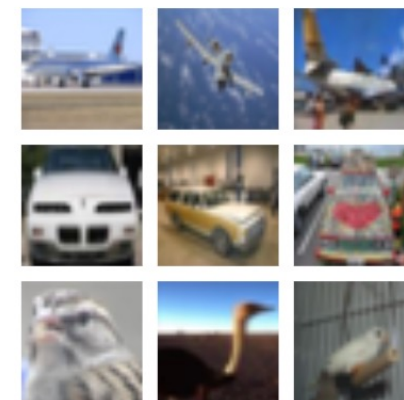
Task: *Image Classification*

Dataset: *CIFAR-100* (Krizhevsky, 2009)



- **Neural guidance improves robustness** (max: 12% accuracy increase) ✓

- **There exists a hierarchy of improvement's magnitude** ✓



Results

l_∞ -based PGD adversarial attack

Task: Image Captioning

Dataset: MSCOCO (Lin et al, 2014)



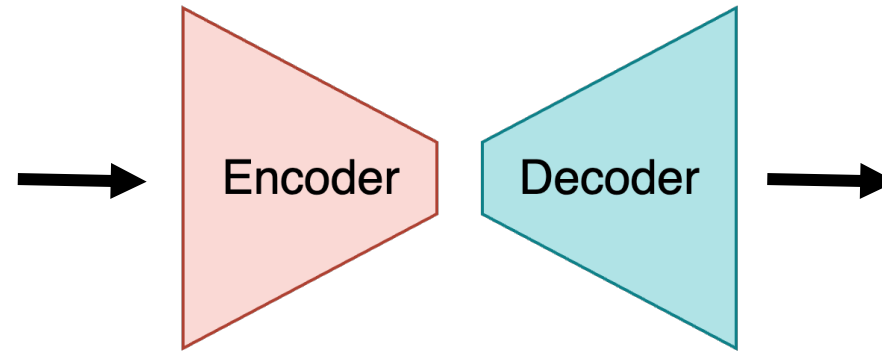
Results

l_∞ -based PGD adversarial attack

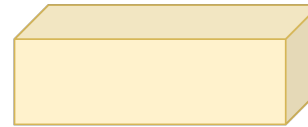
Task: *Image Captioning*

Dataset: *MSCOCO* (Lin et al, 2014)

- Do representations from neurally-guided DNNs benefit other visual tasks beyond basic classification?



“Happy dog sitting in the bed of a pickup truck.”



(“Show, Attend, & Tell”, Xu et al., 2015)

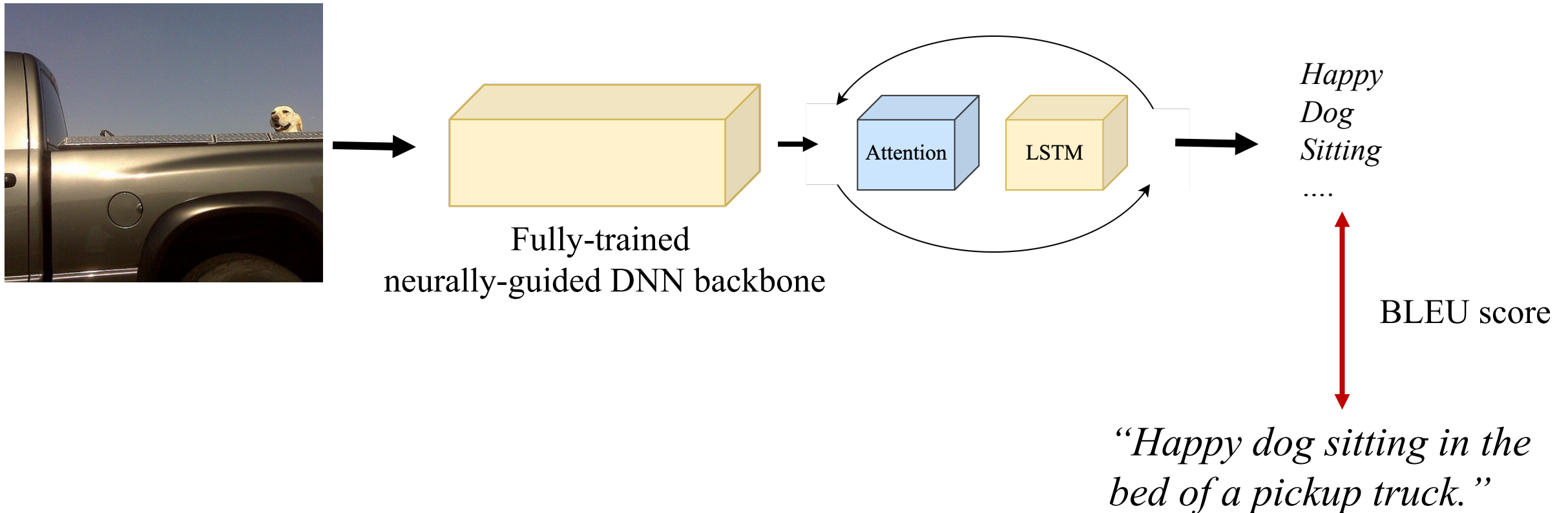
Results

l_∞ -based PGD adversarial attack

Task: Image *Captioning*

Dataset: *MSCOCO* (Lin et al, 2014)

- Do representations from neurally-guided DNNs benefit other visual tasks beyond basic classification?



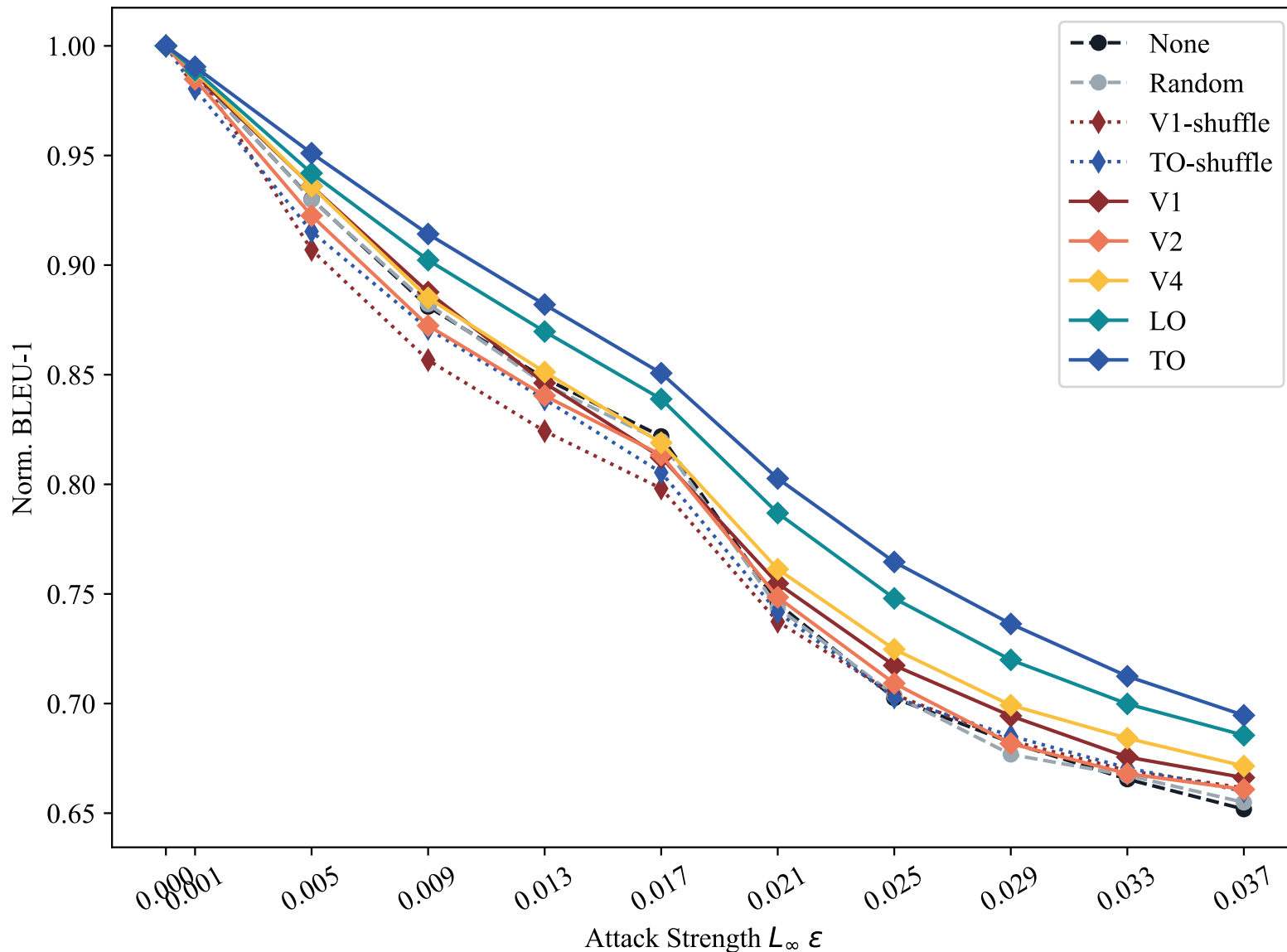
(“Show, Attend, & Tell”, Xu et al., 2015)

Results

l_∞ -based PGD adversarial attack

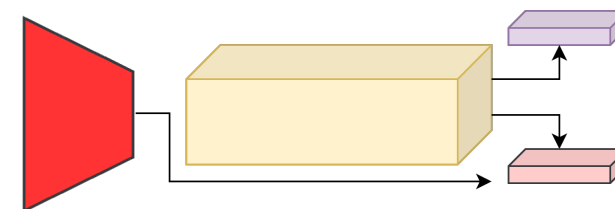
Task: *Image Captioning*

Dataset: *MSCOCO* (Lin et al., 2014)



- **Neural regularization improves robustness** (max: 0.03 BLEU-1 increase) ✓

- **There exists a hierarchy of improvement's magnitude** ✓

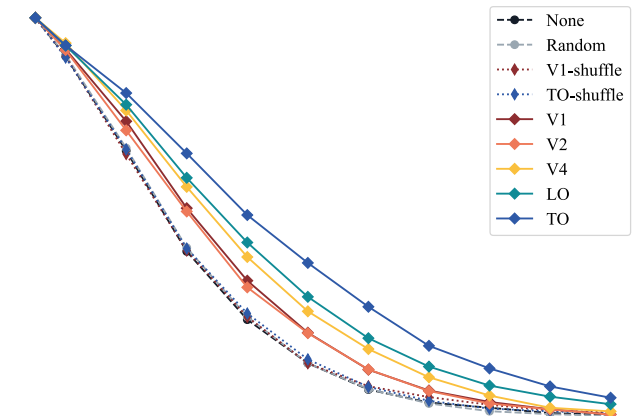
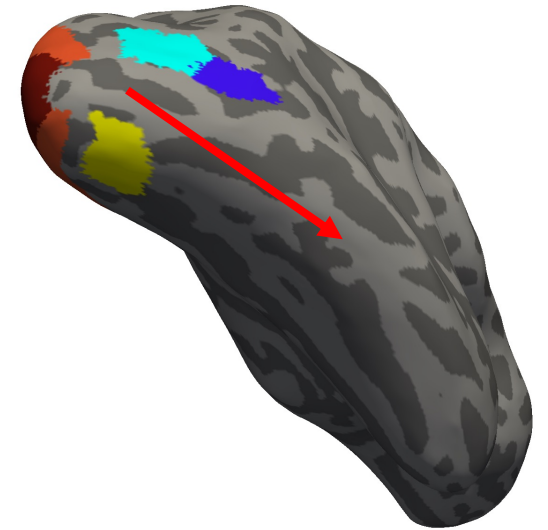


Neural-guidance

→ Robust feature extractor

Conclusion & Discussion

- We found **hierarchical improvements** in DNN **robustness** across:
 - Datasets (ImageNet, CIFAR-100, MSCOCO)
 - Tasks (Classification, Captioning)
 - Attacks (L_∞ PGD, L_∞ FGSM, Autoattack, L_2 FGM, L_2 Deepfool)
- Implications:
 - Evolving representation space along ventral visual stream
 - Learnable and improvable with generic DNN structures
 - Potential for uncovering principles of building human-like representation space and advancing DNN architectural development
- **Further analysis**
 - Neurally-guided models are more shape-biased
 - Smoother output surface achieved in a different way from conventional solutions.
 - Neurally-guided models experience profound changes in their representation space



Acknowledgement



Linjian Ma



Bo Li



Diane M. Beck



This work used NCSA Delta GPU through allocation SOC230011 from the Advanced Cyberinfrastructure Coordination Ecosystem: Services & Support (ACCESS) program, which is supported by National Science Foundation grants #2138259, #2138286, #2138307, #2137603, and #2138296.